



We safeguard the movements of this world



Specialists in power transmission for more than a century

mayr® power transmission is one of the most traditional and yet most innovative German companies in the field of power transmission. From modest beginnings in the year 1897, the family enterprise from the Allgäu region has developed into the world market leader. Today, approximately 700 employees work at the headquarters in Mauerstetten; about 1200 employees work for the company worldwide.

An unsurpassed standard product range

mayr® power transmission offers a wide variety of torque limiters, safety brakes, backlash-free shaft misalignment compensation couplings and high-quality DC drives. Regarding customer-specific requirements, too, the company possesses the expertise to develop customized and economical solutions. This is why numerous renowned machine manufacturers trust in holistic solutions by mayr® power transmission.

Represented worldwide

With eight subsidiaries in Germany, sales offices in the USA, France, Great Britain, Italy, Singapore and Switzerland as well as 36 additional country representatives, $mayr^{\tiny{(0)}}$ is available in all important industrial areas, guaranteeing optimum customer service around the globe.

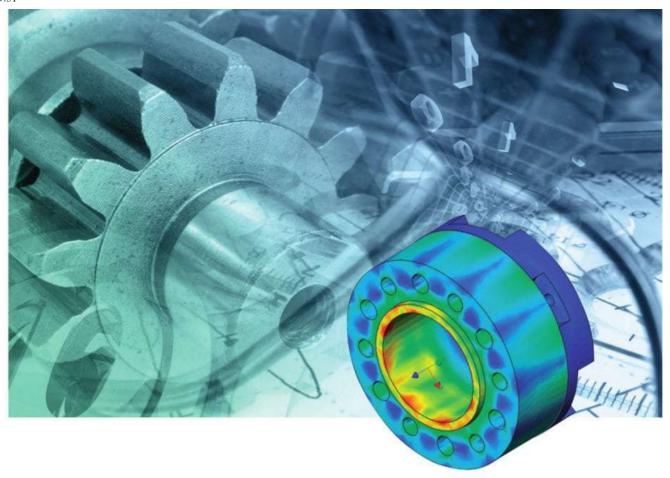
Never compromise on safety

We make no compromises where safety is concerned. Only top products of a perfect quality guarantee that no people are injured or machines damaged in case of malfunctions, collisions and other hazardous situations. The safety of your employees and machines is our motivation to always provide the best and most reliable clutches, couplings or brakes.

mayr[®] power transmission holds numerous ground-breaking patents, and is the global market or technological leader for

- application-optimised safety brakes, for example for passenger elevators, stage technology and gravity-loaded axes
- torque limiters to protect against expensive overload damage and production losses and
- backlash-free servo couplings.





Tradition and innovation – the best of both worlds

Tradition and innovation do not contradict each other - on the contrary. They are the two supporting pillars which have guaranteed stability and reliability for generations. Long-term stability, independence as well as a good reputation and satisfied customers are important values for a family enterprise rich in tradition.

Therefore, we place emphasis on:

- Tested product quality,
- · Optimum customer service,
- Comprehensive know-how,
- Global presence,
- Successful innovations and
- Effective cost management.

By pursuing our own objective of always offering our customers the technologically most advanced and most economical solution, we have been able to gain the trust of many leading industrial companies from all branches and from all over the world as a reliable partner.

Place your trust in our know-how and our more than 50 years of experience in the areas of torque limiters, safety brakes and shaft couplings.

Tested quality and reliability

mayr® products are subject to meticulous quality inspections. These include quality assurance measures during the design process as well as a comprehensive final inspection. Only the best, tested quality leaves our place of manufacture. All products are rigorously tested on calibrated test stands, and adjusted precisely to the requested values. An electronic database in which the measurement values are archived together with the associated serial numbers guarantees 100 % traceability. On request, we confirm the product characteristics with a test protocol.

The certification of our quality management according to DIN EN ISO 9001:2000 confirms the quality-consciousness of our colleagues at every level of the company.





EAS®-compact® - the economically viable protection for machines

Function

If the set limit torque is exceeded, the clutch disengages. The torque drops immediately. A mounted limit switch registers the disengagement movement and switches off the drive. The limit switch signal can also be used for further control functions.

After the malfunction has been rectified, the EAS®-compact® ratchetting clutches and the EAS®-compact® synchronous clutches automatically re-engage (for a detailed description of the re-engagement behaviour, see page 5).

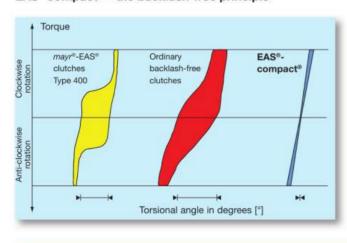
Overload clutches of the series EAS®-compact® -F separate the drive end and the output side completely and remain in this state until they are intentionally re-engaged by hand or via a suitable device. Detailed description see catalogue K.4190.V__.EN.



The EAS®-compact® matrix for success

roduct characteristics	Your advantages	Your benefits
Backlash-free torque transmission	Long lifetime, Low wear	Lowest maintenance effort
Safe, readable torque adjustment	Simple installation and operation	Time-saving during initial operation
High performance density	Low mass moment of inertia, compact construction	High machine dynamic
Convenient torque course in the drive line on overload	Optimised dimensioning	Effective and efficient machine construction

EAS®-compact® - the backlash-free principle



Backlash means:

- The torsional angle between the input and output of the clutch
- Also known an "torsional backlash"
- Not to be confused with the transmission backlash from the shaft onto the hub
- At mayes, backlash-free means: Backlash > 0 (see diagram)



EAS®-compact®/EAS®-NC Ratchetting clutch



- When the set limit torque is reached, the clutch disengages; the torque drops immediately.
- The clutch ratchets.
- After the cause of overload has been removed, the clutch automatically re-engages into the next of the series of ball detents.
- The clutch is ready for operation again.

EAS®-compact®/EAS®-NC Synchronous clutch



- When the set limit torque is reached, the clutch disengages; the torque drops immediately.
- After the cause of overload has been removed, the clutch re-engages automatically after 360 angular degrees.
 Other cycle sequences, for example 180 degrees, are also available.
- The clutch is ready for operation again.

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For small torques:

EAS®-NC ratchetting clutches EAS®-NC synchronous clutches

Torque range: 0.65 to 15 Nm

Data sheets

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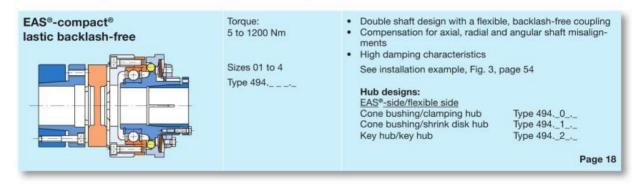


Summary of constructional designs EAS®-compact® ratchetting clutch/ synchronous clutch

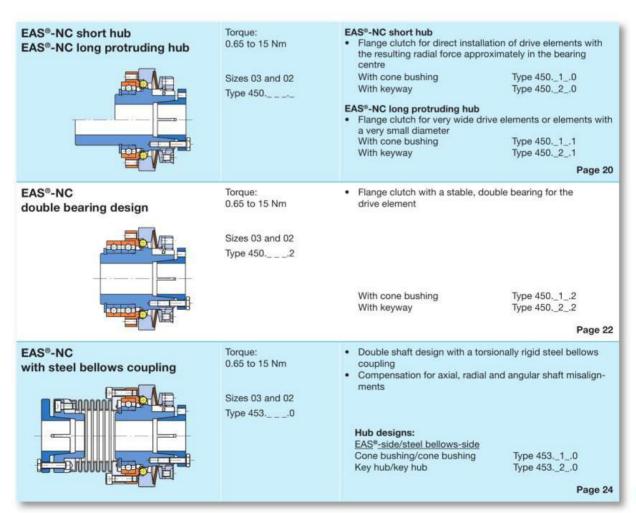
EAS®-compact® Torque: 5 to 1500 Nm Flange clutch for direct installation of the drive element with the resulting radial force approximately in the bearing short hub centre See installation example, Fig. 1, page 54 Sizes 01 to 4 Type 490.___.0 Also available in With cone bushing Type 490. 1 .0 With keyway rustproof design! Type 490. 2 .0 Page 8 EAS®-compact® Torque: Flange clutch with a stable, double bearing for the drive 5 to 1500 Nm element double bearing design Sizes 01 to 4 Type 490.___.2 Type 490._1_.2 With cone bushing With keyway Type 490. 2 .2 Page 10 EAS®-compact® Torque: Flange clutch for very wide drive elements or elements with 5 to 1500 Nm a very small diameter long protruding hub Suitable bearings for the drive element are ball bearings, needle bearings or plain bearings. Sizes 01 to 4 See installation example, Fig. 2, page 54 Type 490.___.1 Type 490._1_.1 With cone bushing With keyway Type 490._2_.1 EAS®-compact® Torque: Double shaft design with a torsionally rigid steel bellows 5 to 350 Nm with steel bellows coupling Compensation for axial, radial and angular shaft misalignments. See installation example, Fig. 4, page 54 Sizes 01 to 3 Hub designs: Type 493. .0 EAS®-side/steel bellows-side Type 493._1_.0 Cone bushing/cone bushing Key hub/key hub Type 493._2_.0 Cone bushing/clamping hub Type 493._3_.0 Page 14 EAS®-compact® torsionally rigid Torque: Double shaft design with a robust disk pack coupling 5 to 1500 Nm Compensation for axial, radial and angular shaft misalign-High torsional rigidity Sizes 01 to 4 Type 496.___.0 **Hub designs:** EAS®-side/torsionally rigid side Cone bushing/shrink disk hub Type 496._1_.0 Key hub/clamping hub Type 496._2_.0 Type 496. 2 .0 Key hub/key hub Page 16



Summary of constructional designs EAS®-compact® ratchetting clutch/synchronous clutch



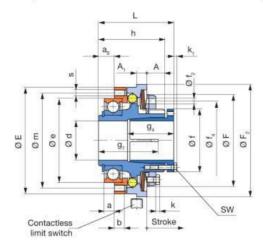
Summary of constructional designs EAS®-NC miniature clutch





EAS®-compact® short hub with cone bushing

Type 490. 1 .0 Sizes 01 to 4

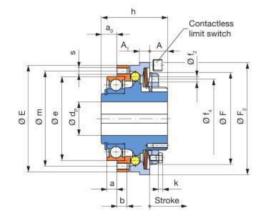




For information on rustproof designs, please order catalogue!

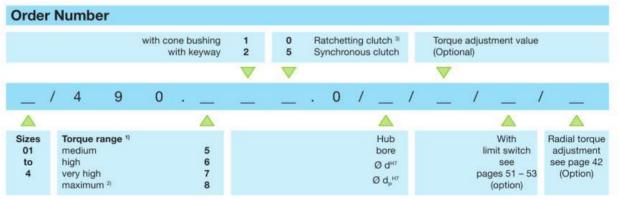
EAS®-compact® short hub with keyway

Type 490. 2 .0 Sizes 01 to 4





For information on rustproof designs, please order catalogue!



Example: Order number 1 / 490.620.0 / 25 / 60 / limit switch 055.002.5 / radial adjustment

- See Technical Data, limit torque for overload $\rm M_{\odot}$ Max. torque range only available as synchronous clutch, speed < 250 rpm
- Standard ratchetting division is 15°; other ratchetting divisions optionally available (45°/60°/90°/120°/180°/...)



Tankainal data				Size 1)							
Technical data				01	0	1	2	3	4		
	Type 490.50	M _g	[Nm]	5 - 12.5	10 - 25	20 - 50	40 – 100	70 – 175	120 - 300		
Limit torques for overload 1) 2)	Type 490.60	M _g	[Nm]	10 - 25	20 - 50	40 – 100	80 - 200	140 - 350	240 - 600		
	Type 490.70	M _g	[Nm]	20 - 50	40 - 100	80 - 200	160 - 400	280 - 700	480 - 1200		
	Type 490.8_ 5.0 11)	Ma	[Nm]	25 - 62.5	50 - 125	100 - 250	200 - 500	350 - 875	600 - 1500		
Max. speed		n _{max}	[rpm]	4000	3000	2500	2000	1200	800		
Thrust washer stroke on overload [mm]		[mm]	1.2	1.5	1.8	2.0	2.2	2.5			

Mass moments of inertia and weights				Size							
				01	0	1	2	3	4		
Unit white	Type 49010	1	[10 ⁻³ kgm ²]	0.211	0.531	1.388	2.846	6.858	29.432		
Hub-side	Type 49020	1	[10 ⁻³ kgm ²]	0.205	0.505	1.302	2.630	6.329	28.443		
Dunnanus flance aide	Type 49010	1	[10 ⁻³ kgm ²]	0.093	0.234	0.643	1.306	2.649	6.690		
Pressure flange-side	Type 49020	1	[10 ⁻³ kgm ²]	0.093	0.234	0.643	1.306	2.649	6.690		
Watehaa	Type 49010	m	[kg]	0.68	1.14	1.98	2.88	4.59	10.63		
Weights	Type 49020	m	[kg]	0.63	1.02	1.75	2.55	4.07	10.06		

Tamatan Inggaran		Size							
Tensioning screws and screw-on bores				01	0	1	2	3	4
	Number, dimensions	M	[mm]	6 x M4	6 x M4	8 x M4	8 x M5	8 x M6	8 x M8
Tensioning screws in cone bushing	Wrench opening	sw	[mm]	7	7	7	8	10	13
	Tightening torque	T	[Nm]	4	4	4	8	12	25
	Number, dimensions	s	[mm]	8 x M4	8 x M5	8 x M6	8 x M6	8 x M8	8 x M10
crew-on bores n pressure flange (12)				Sc	rews quality cla	ss 12.9 must be	used to secure	the drive elem	ent.

Dimensions I				Size								
Dimensions [mmj	01	0	1	2	3	4					
A	Α			16	17	20.5	46					
A,		7	8	9	10	12	16					
a ^{s)}		5	7	9	10	10	12					
a _o		8	11	14	16	18	21					
b		6	7	9	10	12	15					
E		65	80	95	110	130	166					
e _{h5} 6)		47	62	75	90	100	130					
F			67	82	97	117	150					
F ₂		70	85	100	115	135	166					
f		38	44	56	70	84	100					
f ₂		5	5	5	6	7	T:					
f ₄		50	55	70	84	100	-					
Minimum	9,	34	39	42	48	53	93					
shaft length	9,	31	36	48	49	62	78					
h	h		48	59	64	75	115					
k		2.8	2.8	3.5	4.0	4.0	7.					
k,	k,		2.8	2.8	3.5	4.0	5.3					
L ⁿ		47	56	67	73	86	130					
m		56	71	85	100	116	150					

Daves Im	Bores [mm]		Size								
bores [m	mj	01	0	1	2	3	4				
d 2) 3) 4)	d _{min}	10	15	22	32	35	40				
Market V	d _{max}	20	25	35	45	55	65				
at 20 to	d _{P min} ⁶⁾	12	15	22	28	32	40				
d _p ^{2) 10)}	d _{P max} 9)	20	25	30	40	50	65				

We reserve the right to make dimensional and constructional alterations.

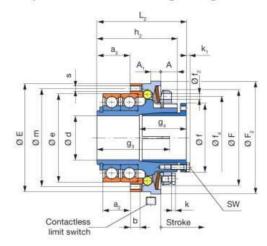
- Further sizes for smaller and larger torques available on request
 Please observe the shaft load in max. torque range.

- 3) Shaft tolerance up to Ø 38 he 38 he 38 he 39 Mark tolerance up to Ø 38 he 39 Mark tolerance up to Ø 38 he 39 Mounting tolerance + 0.1
- 6) Tolerance user-side H7
- 7) Dimensions in untensioned condition (shorter in tensioned condition)
 8) Smaller bores for low torques available on request
- 9) Larger bores available on request
- The position of the keyway to the mounting bore "s" in the pressure flange is not defined. Defined position available on request 11) Maximum speed: 250 rpm
- 12) The screw-on bores in the pressure flange are not angle-synchronous to the hub keyway in the standard version.



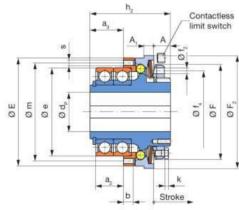
EAS®-compact® double bearing design with cone bushing

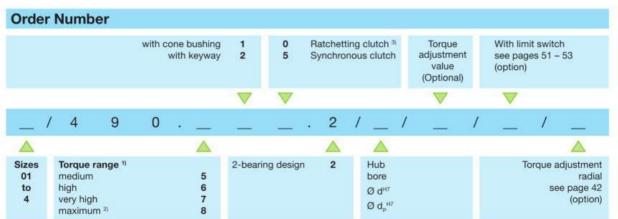
Type 490. 1 .2 Sizes 01 to 4



EAS®-compact® double bearing design with keyway

Type 490. 2 .2 Sizes 01 to 4





Example: Order number 1 / 490.610.2 / 25 / 60 / limit switch 055.002.5 / radial adjustment

See Technical Data, limit torque for overload M_a

- 2) Max. torque range only available as synchronous clutch, speed < 250 rpm
 3) Standard ratchetting division is 15°; other ratchetting divisions optionally available (45°/60°/90°/120°/180°/...)



To about and alone				Size 11							
Technical data	ecimical data			01	0	1	1 2	3	4		
	Type 490.52	Mg	[Nm]	5 - 12.5	10 - 25	20 - 50	40 – 100	70 – 175	120 - 300		
Limit torques for overload 1)2)	Type 490.62	Ma	[Nm]	10 – 25	20 - 50	40 – 100	80 – 200	140 - 350	240 - 600		
	Type 490.72	Ma	[Nm]	20 - 50	40 - 100	80 – 200	160 - 400	280 - 700	480 - 1200		
	Type 490.8_ 5.2 119	M _c	[Nm]	25 - 62.5	50 - 125	100 – 250	200 - 500	350 - 875	600 - 1500		
Max. speed		n _{max}	[rpm]	4000	3000	2500	2000	1200	800		
Thrust washer stroke on overload			[mm]	1.2	1.5	1.8	2.0	2.2	2.5		

Mass moments of inertia and weights				Size							
				01	0	1	2	3	4		
Hub-side	Type 49012	1	[10 ⁻³ kgm ²]	0.215	0.552	1.450	2.998	7.081	30.990		
nub-side	Type 49022	1	[10 ⁻³ kgm ²]	0.209	0.526	1.364	2.782	6.552	30.000		
Danas danas alda	Type 49012	1	[10 ⁻³ kgm ²]	0.100	0.273	0.799	1.675	3.162	8.570		
Pressure flange-side	Type 49022	1	[10 ⁻³ kgm ²]	0.100	0.273	0.799	1.675	3.162	8.570		
W-1-b4-	Type 49012	m	[kg]	0.79	1.35	2.35	3.45	5.27	11.96		
Weights	Type 49022	m	[kg]	0.74	1.23	2.12	3.12	4.75	11.35		

Tensioning screw	s and screw-on b	ore	S	Size							
				01	0	1	2	3	4		
	Number, dimensions	M	[mm]	6 x M4	6 x M4	8 x M4	8 x M5	8 x M6	8 x M8		
Tensioning screws in cone bushing	Wrench opening	SW	[mm]	7	7	7	8	10	13		
	Tightening torque	TA	[Nm]	4	4	4	8	12	25		
Screw-on bores in pressure flange (12)	Number, dimensions	s	[mm]	8 x M4	8 x M5	8 x M6	8 x M6	8 x M8	8 x M10		
				Sci	rews quality cla	ss 12.9 must be	used to secure	the drive elem	ent.		

Dimensions I		Size									
Dimensions [mmj	01	0	1	2	3	4				
А		12	13.5	16	17	20.5	46				
A,		7	8	9	10	12	16				
a ₂ 5)		14	19	25	28	28	34				
a ₃		17	23	30	34	36	43				
b		6	7	9	10	12	15				
E		65	80	95	110	130	166				
e _{h5} 6)		47	62	75	90	100	130				
F		61.5	67	82	97	117	150				
F ₂		70	85	100	115	135	166				
f		38	44	56	70	84	100				
f,		5	5	5	6	7	-				
f,		50	55	70	84	100	-				
Minimum	g _a	40	48	63	67	80	100				
shaft length	g,	34	39	42	48	53	93				
h ₂		49	60	75	82	93	137				
k		2.8	2.8	3.5	4.0	4.0	-				
k,		2.8	2.8	2.8	3.5	4.0	5.3				
L ₂ 79		56	68	83	91	104	152				
m		56	71	85	100	116	150				

Davas Im	1		Size								
Bores [m	mI	01	0	1	2	3	4				
d 2) 3) 4)	d _{min}	10	15	22	32	35	40				
(Martin	d _{max}	20	25	35	45	55	65				
at 20 10)	d _{P min} 8)	12	15	22	28	32	40				
d _p ^{2) 10)}	d _{P max} 9)	20	25	30	40	50	65				

We reserve the right to make dimensional and constructional alterations.

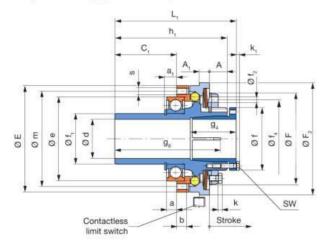
- Further sizes for smaller and larger torques available on request
 Please observe the shaft load in max. torque range.

- 3) Shaft tolerance up to Ø 38 _{se}, over Ø 38 _{id}
 4) Transmittable torques available with smaller bores on request
 5) Mounting tolerance + 0.1
- 6) Tolerance user-side H7
- 7) Dimensions in untensioned condition (shorter in tensioned condition) 8) Smaller bores for low torques available on request
- 9) Larger bores available on request
- The position of the keyway to the mounting bore "s" in the pressure flange is not defined. Defined position available on request 11) Maximum speed: 250 rpm
- 12) The screw-on bores in the pressure flange are not angle-synchronous to the hub keyway in the standard version.



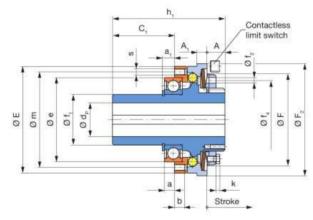
EAS®-compact®long protruding hub with cone bushing

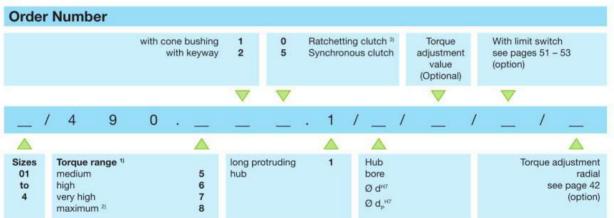
Type 490. 1 .1 Sizes 01 to 4



EAS®-compact® long protruding hub with keyway

Type 490. 2 .1 Sizes 01 to 4





Example: Order number 1 / 490.610.1 / 25 / 60 / limit switch 055.002.5 / radial adjustment

12

- See Technical Data, limit torque for overload $\rm M_{\odot}$ Max. torque range only available as synchronous clutch, speed < 250 rpm
- Standard ratchetting division is 15°; other ratchetting divisions optionally available (45°/60°/90°/120°/180°/...)

1/2



Tankai and data	Type 490.61 M _a [N Type 490.81 M _a [N Type 490.81 M _a [N Type 490.81 M _a [N Type 490.85.1 M _a [N Type 490.8			Size 1								
recnnical data				01	0	1	2	3	4			
	Type 490.51	Mg	[Nm]	5 - 12.5	10 - 25	20 - 50	40 – 100	70 – 175	120 - 300			
Grenzdrehmomente	Type 490.61	Ma	[Nm]	10 – 25	20 - 50	40 – 100	80 – 200	140 - 350	240 - 600			
für Überlast 1) 2)	Type 490.71	Ma	[Nm]	20 - 50	40 - 100	80 - 200	160 - 400	280 - 700	480 -1200			
	Type 490.8_ 5.1 11)	Mg	[Nm]	25 - 62.5	50 - 125	100 - 250	200 - 500	350 - 875	600 - 1500			
Max. speed		n _{max}	[rpm]	4000	3000	2500	2000	1200	800			
Thrust washer stroke	on overload		[mm]	1.2	1.5	1.8	2.0	2.2	2.5			

Mass manages	6 imanda amala		ula to			Si	ze		
mass moments o	b-side Type 49021 I [10-3 kgm² Type 49011 I [10-3 kgm² Type 49011 I [10-3 kgm²				0	1	2	3	4
Units adds	Type 49011	1	[10 ⁻³ kgm ²]	0.225	0.588	1.491	3.105	7.350	30.890
nub-side	Type 49021	1	[10 ⁻³ kgm ²]	0.219	0.562	1.405	2.889	6.851	29.900
D	Type 49011	1	[10 ⁻³ kgm ²]	0.093	0.234	0.643	1.306	2.649	6.690
Pressure nange-side	Type 49021	1	[10 ⁻³ kgm ²]	0.093	0.234	0.643	1.306	2.649	6.690
Weights	Type 49011	m	[kg]	0.78	1.36	2.26	3.34	5.18	11.65
weights	Type 49021	m	[kg]	0.73	1.24	2.04	3.00	4.66	11.04

Toncionina corow	s and screw-on b	oro				Si	ze		
rensioning screw	s and screw-on L	ore	3	01	0	1	2	3	4
	Number, dimensions	M	[mm]	6 x M4	6 x M4	8 x M4	8 x M5	8 x M6	8 x M8
ensioning screws cone bushing	Wrench opening	SW	[mm]	7	7	7	8	10	13
in cone bushing	Tightening torque	T	[Nm]	4	4	4	8	12	25
	Number, dimensions	s	[mm]	8 x M4	8 x M5	8 x M6	8 x M6	8 x M8	8 x M10
Screw-on bores in pressure flange (12)				Sci	rews quality cla	ss 12.9 must be	used to secure	the drive elem	ent.

Dimensions [mm]	Size									
Dimensions [mm]	01	0	1	2	3	4				
Α	12	13.5	16	17	20.5	46				
A,	7	8	9	10	12	16				
a ⁵⁾	5	7	9	10	10	12				
a,	6.5	8.75	11.5	13	14	16				
b	6	7	9	10	12	15				
C,	33	43	55	67	73	76				
E	65	80	95	110	130	166				
e _{h5} 6)	47	62	75	90	100	130				
F	61.5	67	82	97	117	150				
F ₂	70	85	100	115	135	166				
f	38	44	56	70	84	100				
f _{1 h6}	30	40	45	55	65	85				
f ₂	5	5	5	6	7	51				
f,	50	55	70	84	100	•				
Minimum 9 ₄	34	39	42	48	53	93				
shaft length g _s	56	68	89	100	117	133				
h,	65	80	100	115	130	170				
k	2.8	2.8	3.5	4.0	4.0	fi				
k,	2.8	2.8	2.8	3.5	4.0	5.3				
L, n	72	88	108	124	141	185				
m	56	71	85	100	116	150				

Daves Inc			Size									
Bores [m	mj	01	0	1	2	3	4					
d 2) 3) 4)	d _{min}	10	15	22	32	35	40					
a	d _{max}	20	25	35	45	55	65					
at 2) 10)	d _{P min} 8)	12	15	22	28	32	40					
d _p ^{2) 10)}	d _{P max} 9)	20	25	30	40	50	65					

We reserve the right to make dimensional and constructional alterations.

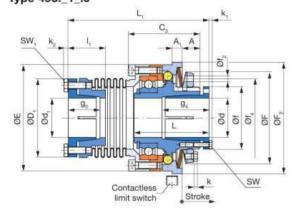
- Further sizes for smaller and larger torques available on request
 Please observe the shaft load in max. torque range.
- 3) Shaft tolerance up to Ø 38 hill over Ø 38 hill
 4) Transmittable torques available with smaller bores on request
 5) Mounting tolerance + 0.1
- 6) Tolerance user-side H7
- 7) Dimensions in untensioned condition (shorter in tensioned condition)
 8) Smaller bores for low torques available on request
- 9) Larger bores available on request
- 10) The position of the keyway to the mounting bore "s" in the pressure flange is not defined. Defined position available on request 11) Maximum speed: 250 rpm
- 12) The screw-on bores in the pressure flange are not angle-synchronous to the hub keyway in the standard version.



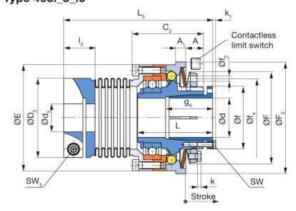
EAS®-compact® with steel bellows coupling

Type 493._ _ .0 Sizes 01 to 3

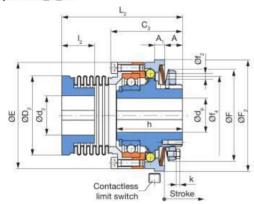
EAS®-side cone bushing, Steel bellows-side cone bushing Type 493._1_.0

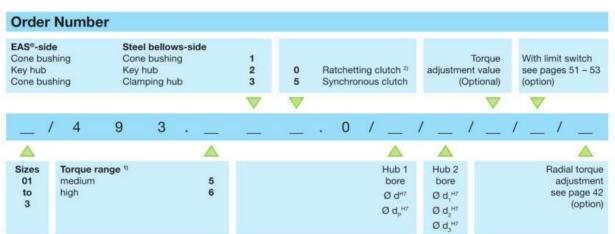


EAS®-side cone bushing, Steel bellows-side clamping hub Type 493._3_.0



EAS®-side key hub, Steel bellows-side key hub Type 493._2_.0





Example: Order number 1 / 493.615.0 / 22 / 25 / 60 / limit switch 055.002.5 / radial adjustment

- 1) See Technical Data, limit torque for overload Ma
- Standard ratchetting division is 15°; other ratchetting divisions optionally available (45°/60°/90°/120°/180°/...)



Tankadad data	rload 1 Type 493.60 M _G [Nm x. speed n _{max} [rpm ust washer stroke on overload minal torques, steel bellows coupling axial ΔK [mm			Size 1)							
recnnicai data				01	0	1	2	3			
Limit torques for	Type 493.50	M _G	[Nm]	5 - 12.5	10 - 25	20 - 50	40 - 100	70 - 175			
overload 1)	Type 493.60	M _G	[Nm]	10 - 25	20 - 50	40 - 100	80 - 200	140 - 350			
Max. speed		n _{max}	[rpm]	4000	3000	2500	2000	1200			
Thrust washer strok	re on overload		[mm]	1.2	1.5	1.8	2.0	2.2			
Nominal torques, ste	eel bellows coupling	T _{KN}	[Nm]	50	100	200	350	600			
	axial	ΔK,	[mm]	0.4	0.6	0.8	1.0	1.0			
Permitted misalignments	radial	ΔK,	[mm]	0.15	0.15	0.20	0.25	0.30			
inisangiments	angular	ΔK _w	[°]	2	2	2	2	2			

	S®-hub-side Type 49320 I [10 ⁻³ kgm Type 49330 I [10 ⁻³ kgm Type 49310 I [10 ⁻³ kgm					Size		
wass moments	or inertia and v	veiç	ints	01	0	1	2	3
	Type 49310	1	[10 ⁻³ kgm ²]	0.211	0.531	1.388	2.846	6.858
EAS®-hub-side	Type 49320	I.	[10 ⁻³ kgm ²]	0.205	0.505	1.302	2.630	6.359
	Type 49330	1	[10 ⁻³ kgm ²]	0.211	0.531	1.388	2,846	6.858
	Type 49310	1	[10 ⁻³ kgm ²]	0.269	0.753	1.764	3.602	7.789
Steel bellows-side	Type 49320	1	[10 ⁻³ kgm ²]	0.249	0.690	1.546	3.018	6.818
	Type 49330	1	[10 ⁻³ kgm ²]	0.286	0.789	1.772	3.773	8.087
	Type 49310	m	[kg]	1.09	1.88	3.08	4.60	7.19
Weights	Type 49320	m	[kg]	1.04	1.76	2.85	4.27	6.90
	Type 49330	m	[kg]	1.22	1.91	3.10	4.65	7.12

Tonoionina ocuo	one bushing "-side Wrench opening Tightening torque Ta Number, dimensions Wrench opening SW [mr Ta INr Number, dimensions Wrench opening SW, [mr				Size							
rensioning scree	NS			01	0	1	2	3				
	Number, dimensions	M	[mm]	6 x M4	6 x M4	8 x M4	8 x M5	8 x M6				
	Wrench opening	SW	[mm]	7	7	7	8	10				
LAG -Side	Tightening torque	TA	[Nm]	4	4	4	8	12				
	Number, dimensions	M,	[mm]	4 x M4	6 xM5	6 x M6	6 x M8	6 x M8				
	Wrench opening	SW,	[mm]	7	8	10	13	13				
steel bellows-side	Tightening torque	T	[Nm]	3	5	9.5	17	17				
to ottomic tone back	Number, dimensions	M ₃	[mm]	1 x M5	1 x M6	1 x M6	1 x M8	1 x M10				
In clamping hub steel bellows-side	Wrench opening	SW ₃	[mm]	4	5	5	6	8				
steel bellows-side	Tightening torque	T	[Nm]	10	18	18	43	87				

Dimensions	[mm]			Size		
Difficusions	formul	01	0	1	2	3
A		12	13.5	16	17	20.5
A,		7	8	9	10	12
C _a		45	53	64	70	81
D,		47	60	70	81	98
D ₂		47	60	71	81	98
D ₃		50	60	71	82	98
E		65	80	95	110	130
F		61.5	67	82	97	117
F ₂		70	85	100	115	135
f		38	44	56	70	84
f ₂		5	5	5	6	7
f,		50	55	70	84	100
Minimum	9 ₄	34	39	42	48	53
shaft length	g _s	24	27	29	32	35
Shart length	1,	24	28	28	36	40
h		40	48	59	64	75
k		2.8	2.8	3.5	4.0	4.0
k,		2.8	2.8	2.8	3.5	4.0
L4)		47	56	67	73	86
L, 4)		93	109	125.5	138	164
L,		77.5	92	107.5	119	140.5
L ₃ ⁴⁾		102	119	133	150	177
1, 4)		27.5	29	33	37	45
1,		25	27	29	36	44

Doro	o Tonom	1			Size		
bore	s [mm	1	01	0	1	2	3
de	d 2) 3)	d _{min}	10	15	22	32	35
EAS®-side	u sist	d _{maa}	20	25	35	45	55
S	a	d _{P min}	12	15	22	28	32
m m	d _p	d _{P max}	20	25	30	40	50
ih	el 2) 3)	d _{1 min}	9	12	15	22	32
š	u,	d _{t max}	20	25	35	42	50
bellc side		d _{2 min}	9	12	15	22	32
Steel bellows	d ₂	d _{2 max}	20 5)	25 ⁽ⁱ⁾	35 7)	42 8)	50
tee	a	d _{3 min}	12	15	25	30	35
S	d ₃	d _{3 max}	25	32	42	45	55

We reserve the right to make dimensional and constructional alterations.

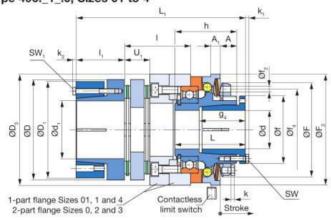
- 1) Further sizes for smaller and larger torques available on request

- Further sizes for smaller and larger torques available on request
 Shaft tolerance up to Ø 38 ₁₆, over Ø 38 ₁₆
 Transmittable torques available with smaller bores on request
 Dimensions in untensioned condition (shorter in tensioned condition)
 Up to Ø 18 keyway acc. DIN 6885/1, over Ø 18 keyway acc. DIN 6885/3
 Up to Ø 22 keyway acc. DIN 6885/1, over Ø 33 keyway acc. DIN 6885/3
 Up to Ø 38 keyway acc. DIN 6885/1, over Ø 38 keyway acc. DIN 6885/3



EAS®-compact® torsionally rigid

EAS®-side cone bushing, ROBA®-DS-side shrink disk hub Type 496._1_.0, Sizes 01 to 4 Type 496._ _ _.0 Sizes 01 to 4

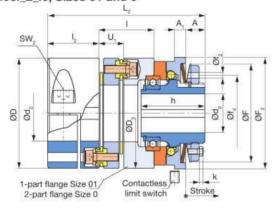


All EAS®-compact® clutches can be combined with almost all components of the ROBA®-DS backlash-free shaft coupling. The Types shown here represent only a selection of the most established designs.

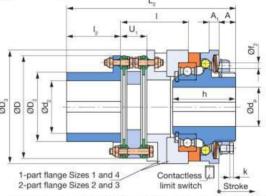
For further combination possibilities, see page 43.

We are happy to advise you on the dimensioning and configuration of your optimum clutch.

EAS®-side key hub, ROBA®-DS-side clamping hub with keyway Type 496. 2_.0, Sizes 01 and 0



EAS®-side key hub, ROBA®-DS-side key hub Type 496._2_.0, Sizes 1 to 4



The missing dimensions (Of, OF and OF,) are identical to Type 496._2_0

Order Number

EAS®-side Cone bushing Key hub ROBA®-DS-side Shrink disk hub Clamping hub ⁴⁾ with keyway (Sizes 01 – 0) / key hub (Sizes 1 – 4)

Ratchetting clutch 3
 Synchronous clutch

Torque adjustment value (Optional)

With limit switch see pages 51 – 53 (option)

Sizes Torque range 1)
01 medium 5
to high 6
4 very high 7
maximum 2) 8

Hub 1 Hub 2 bore bore Ø d₁^{H7} Ø d₂^{H7}

Radial torque adjustment see page 42 (option)

Example: Order number 1 / 496.625.0 / 22 / 25 / 60 / limit switch 055.002.5 / radial adjustment

2

- 1) See Technical Data, limit torque for overload M_s
- Max. torque range only available as synchronous clutch, speed < 250 rpm
- Standard ratchetting division is 15°; other ratchetting divisions optionally available (45°/60°/90°/120°/180°/...)
- 4) Clamping hub also available without keyway (Sizes 01-0)



Tooknieel dete						Size 1)			
Technical data				01	0	1	2	3	4
	Type 496.50	M _G	[Nm]	5 – 12.5	10 - 25	20 - 50	40 – 100	70 – 175	120 - 300
Limit torques for	Type 496.60	M _G	[Nm]	10 - 25	20 - 50	40 - 100	80 - 200	140 - 350	240 - 600
overload 1)	Type 496.70	M _G	[Nm]	20 - 50	40 - 100	80 - 200	160 - 400	280 - 700	480 - 1200
	Type 496.8_ 5.0 5)	M _G	[Nm]	25 - 62.5	50 - 125	100 - 250	200 - 500	350 - 875	600 - 1500
Max. speed		n _{max}	[rpm]	4000	3000	2500	2000	1200	800
Thrust washer strol			[mm]	1.2	1.5	1.8	2.0	2.2	2.5
Nominal torques, tor	sionally rigid coupling	TKN	[Nm]	100	150	300	650	1100	1600
	axial ⁶⁾	ΔK	[mm]	0.9	1.1	0.8	1.1	1.3	1.5
Permitted nisalignments	radial	ΔK,	[mm]	0.20	0.20	0.20	0.25	0.30	0.30
illisaligilillellis	angular	ΔK _w	[°]	2.0	2.0	1.4	1.4	1.4	1.4

Mana managara	ad in autic and o		-lata			Si	ze		
wass moments	of inertia and v	veig	gnts	01	0	1	2	3	4
EACO but alds	Type 49610	1	[10 ⁻³ kgm ²]	0.211	0.531	1.388	2.846	6.858	29.432
EAS*-nub-side	Type 49620	1	[10 ⁻³ kgm ²]	0.205	0.505	1.302	2.630	6.359	28.443
DODAS DO -ld-	Type 49610	1	[10 ⁻³ kgm ²]	0.849	2.395	2.915	9.543	21.443	38.996
HUBADS-side	Type 49620	I.	[10 ⁻³ kgm ²]	0.709	2.086	2.417	7.815	18.215	31.480
Watehta	Type 49610	m	[kg]	1.63	2.95	3.80	7.04	11.45	19.16
AS®-hub-side T OBA®-DS-side T I leights	Type 49620	m	[kg]	1.43	2.61	3.50	6.35	10.81	17.31

Tonnioning core						Si	ze		
Tensioning scre	ws			01	0	1	2	3	4
	Number, dimensions	M	[mm]	6 x M4	6 x M4	8 x M4	8 x M5	8 x M6	8 x M8
In cone bushing EAS®-side	Wrench opening	SW	[mm]	7	7	7	8	10	13
EAS -Side	Tightening torque	T _A	[Nm]	4	4	4	8	12	25
1 10 100 1000	Number, dimensions	M,	[mm]	4 x M5	6 x M5	6 x M5	6 x M5	6 x M6	6 x M8
In shrink disk ROBA®-DS-side	Wrench opening	SW,	[mm]	8	8	8	8	10	13
HODA - DO-Side	Tightening torque	T	[Nm]	6	6	6	8.5	10	25
	Number, dimensions	M,	[mm]	1 x M8	1 x M8	27	E#12	223	
In clamping hub ROBA®-DS-side	Wrench opening	SW,	[mm]	6	6	-	(40)		(*)
NODA -DS-SIGE	Tightening torque	T,	[Nm]	33	33	- 2	120	121	120

Dimensione [mm]			Si	ze		
Dimensions [mm]	01	0	1	2	3	4
A	12	13.5	16	17	20.5	46
A,	7	8	9	10	12	16
D	69	79	77	104	123	143
D,	68	78	77	100	115	143
D ₂	+	-	50	70	80	100
D ₃	69	85	100	115	135	172
F	61.5	67	82	97	117	150
F ₂	70	85	100	115	135	166
f	38	44	56	70	84	100
f	5	5	5	6	7	#1
f,	50	55	70	84	100	
min. Wellenlänge g ₄	34	39	42	48	53	93
h	40	48	59	64	75	115
k	2.8	2.8	3.5	4.0	4.0	-
k,	2.8	2.8	2.8	3.5	4.0	5.3
k ₂	3.5	3.5	3.5	3.5	4.0	5.3
L4)	47	56	67	73	86	130
L,4	105.3	132.8	141.2	175.2	208	237
L ₂	98.3	120.3	133.2	171.2	207	237
	34.3	49.8	48.2	68.2	85	68
I,	32	37.5	40	50	55	60
l ₂	32	33.5	40	55	65	75
U,	15.3	15.8	21.2	26.2	34	35.2

D	- F				Si	ze	Size								
bore	s [mn	nj	01	0	1	2	3	4							
	d 2)	d _{min}	10	15	22	32	35	40							
de Se	u ···	d _{max}	20	25	35	45	55	65							
EAS®-	side	d _{P min}	12	15	22	28	32	40							
	d _p	d _{P max}	20	25	30	40	50	65							
Ġ	-1 30	d _{t min}	19	25	25	40	45	55							
e P	d, 3)	d _{1 max}	38	45	45	60	70	90							
ROBA®-DS side		d _{2 min}	19	25	16	25	30	35							
8	d ₂	d _{2 max}	35	42	32	50	55	70							

We reserve the right to make dimensional and constructional alterations.

- 1) Further sizes for smaller and larger torques available on request
 2) Shaft tolerance up to Ø 38 he, over Ø 38 he
 3) Recommended shaft tolerance ye
 4) Dimensions in untensioned condition (shorter in tensioned condition)
 5) Maximum speed: 250 rpm
 6) Only permitted as a static or virtually static value.



Type 494.__._ EAS®-compact® lastic backlash-free Sizes 01 to 4 EAS®-side cone bushing, EAS®-side cone bushing, ROBA®-ES-side clamping hub ROBA®-ES-side shrink disk hub Type 494._0_._ Type 494._1_._ C C OD, po pd ØD, OD B PF 00 PØ 8 70 Contactless Contactless limit switch limit switch Stroke Stroke The missing dimensions (Of, Of,, OF and ØF.) are identical to Type 494._0_._ EAS®-side key hub, ROBA®-ES-side key hub Contactless Type 494._2_._ limit switch 10 OD. OD po PF pa PF 6 Stroke **Order Number** EAS®-side ROBA®-ES-side Cone bushing Clamping hub With limit switch Torque Cone bushing Shrink disk hub 0 Ratchetting clutch 2) adjustment value see pages 51 - 53 Key hub 5 Synchronous clutch Key hub (Optional) (Option) 4 4 Sizes Hub 1 Hub 2 Torque range 1) Flexible coupling Radial torque 01 medium 5 92 Shore A 3 bore bore adjustment to 98 Shore A see page 42 Ø d,F7 Ø d^{H7} very high 64 Shore D 6 (option) Ø d, H7 Ø d, H7 Ød, H Example: Order number 1 / 494.615.3 / 22 / 25 / 60 / limit switch 055.002.5 / radial adjustment See Technical Data, limit torque for overload M_q Standard ratchetting division is 15°; other ratchetting divisions optionally on page 50. Shaft tolerance up to Ø 38 $_{\rm hir}$ over Ø 38 $_{\rm hi}$ Transmittable torques available with smaller bores on request available (45°/60°/90°/120°/180°/...) The transmittable torques on the flexible coupling "Txo Smaller bores for smaller torques available on request on factors such as Temperature factor, torsional rigidity, etc., see also coupling dimensioning ROBA®-ES catalogue K.940.V__ or contact the Larger bores available on request Shaft tolerance up to Ø 40 , manu-facturer. Furthermore, the transmittable torques of the flexible Keyway 180° offset to "G" coupling are dependent on the bore diameter $d_{\scriptscriptstyle 3}$ or $d_{\scriptscriptstyle 4}$, see also Table 1 10) Dimensions in untensioned condition (shorter in tensioned condition)



Tankaisal data							Size			
Technical data					01	0	1	2	3	4
t toota a conversa de u	Type 49	4.5	M _G	[Nm]	5-12.5	10-25	20 - 50	40 - 100	70 – 175	120 - 300
Limit torques for overload 3	Type 49	4.6	M _G	[Nm]	10-25	20 - 50	40 - 100	80 - 200	140 - 350	240 - 600
overioau	Type 494.7		Ma	[Nm]	20 - 50	40 - 100	80 - 200	160 - 400	280 - 700	480 - 1200
Max. speed			n _{max}	[rpm]	4000	3000	2500	2000	1200	800
Thrust washer stroke on overload			[mm]	1.2	1.5	1.8	2.0	2.2	2.5	
Nominal and maxi-		92 Shore A	T _{KN} /T _{max}	[Nm]	35 / 70	95 / 190	190 / 380	265 / 530	310 / 620	900 / 1800
mum torques 3),		98 Shore A	T _{KN} /T _{max}	[Nm]	60 / 120	160 / 320	325 / 650	450 / 900	525 / 1050	1040 / 2080
flexible coupling		64 Shore D	T _{KN} /T _{max}	[Nm]	75 / 150	200 / 400	405 / 810	560 / 1120	655 / 1310	1250 / 2500
	axial		ΔK,	[mm]	1.4	1.5	1.8	2.0	2.1	2.6
		92 Shore A	ΔK,	[mm]	0.14	0.15	0.17	0.19	0.21	0.25
	radial	98 Shore A	ΔK,	[mm]	0.10	0.11	0.12	0.14	0.16	0.18
Permitted misalignments		64 Shore D	ΔK,	[mm]	0.07	0.08	0.09	0.10	0.11	0.13
misangiments		92 Shore A	ΔK _w	[°]	1.0	1.0	1.0	1.0	1.0	1.0
	angular	98 Shore A	ΔK _w	[°]	0.9	0.9	0.9	0.9	0.9	0.9
		64 Shore D	ΔK _w	[°]	0.8	0.8	0.8	0.8	0.8	0.8

Mass mamanta	of inautic and u		white	Size						
wass moments	of inertia and v	veig	gnts	01	0	1	2	3	4	
	Type 4940	1	[10 ⁻³ kgm ²]	0.211	0.531	1.388	2.846	6.858	29.432	
EAS®-hub-side	Type 4941	1	[10 ⁻³ kgm ²]	0.211	0.531	1.388	2.846	6.858	29.432	
	Type 4942	1	[10 ⁻³ kgm ²]	0.205	0.505	1.302	2.630	6.359	28.443	
	Type 4940	1	[10 ⁻³ kgm ²]	0.322	0.700	1.846	7.627	14.530	48.570	
ROBA®-ES-side	Type 4941	1	[10 ⁻³ kgm ²]	0.381	0.833	2.280	7.475	14.167	43.038	
	Type 494. 2	1	[10 ⁻³ kgm ²]	0.324	0.696	1.847	7.613	14.520	49.106	
	Type 4940	m	[kg]	1.06	1.58	2.69	6.31	9.23	21.53	
/eights	Type 4941	m	[kg]	1.18	1.74	3.05	6.20	8.91	21.44	
	Type 494. 2	m	[kg]	1.02	2.09	2.70	6.23	9.56	21.09	

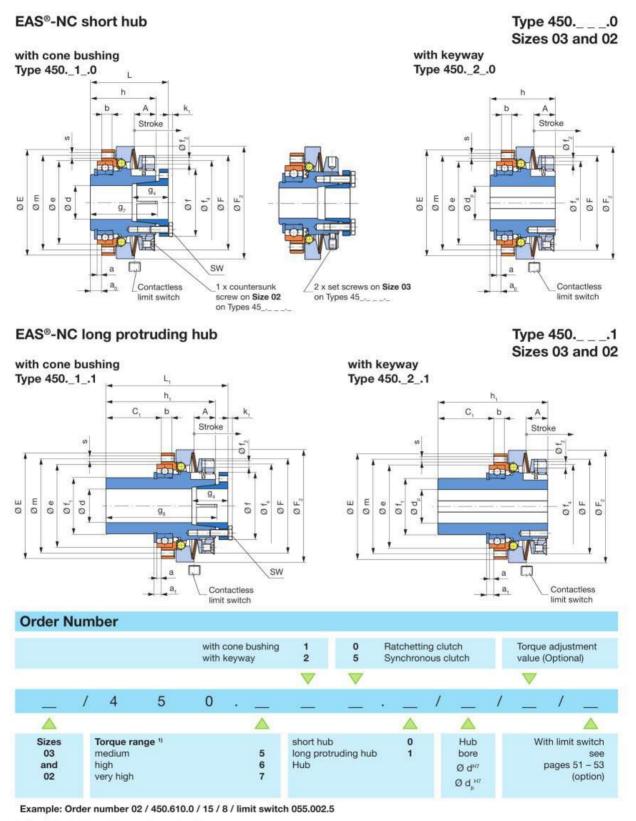
Tanalanina assa				Size							
Tensioning scre	ews			01	0	1	2	3	4		
	Number, dimensions	M	[mm]	6 x M4	6 x M4	8 x M4	8 x M5	8 x M6	8 x M8		
In cone bushing EAS®-side	Wrench opening	SW	[mm]	7	7	7	8	10	13		
EAS*-Side	Tightening torque	T	[Nm]	4	4	4	8	12	25		
1 2 2 2 2	Number, dimensions	M,	[mm]	1 x M6	1 x M8	1 x M8	1 x M10	1 x M12	1 x M14		
In clamping hub ROBA®-ES-side	Wrench opening	SW,	[mm]	5	6	6	8	10	12		
HODA -E3-Side	Tightening torque	T	[Nm]	10.5	25	25	70	120	200		
e de la companya de	Number, dimensions	M,	[mm]	4 x M5	8 x M5	8 x M6	4 x M8	4 x M8	4 x M12		
In shrink disk	Wrench opening	SW,	[mm]	4	4	5	6	6	10		
ROBA®-ES-side	Tightening torque	T,	[Nm]	6	6	10.5	25	30	90		

Dimensions [mm]			Si	ze		
Dimensions [mm]	01	0	1	2	3	4
Α	12	13.5	16	17	20.5	46
A,	7	8	9	10	12	16
C,	47	56.5	69	74	87	130
D,	70	85	100	115	135	175
D _H	55	65	80	95	105	135
F	61.5	67	82	97	117	150
F ₂	70	85	100	115	135	166
f	38	44	56	70	84	100
f ₂	5	5	5	6	7	-
f ₄	50	55	70	84	100	-
G ^{sp}	M5	M6	M8	M8	M8	M10
min. Wellenlänge g,	34	39	42	48	53	93
h	40	48	59	64	75	115
k	2.8	2.8	3.5	4.0	4.0	-
k,	2.8	2.8	2.8	3.5	4.0	5.3
L 10)	47	56	67	73	86	130
L, 10)	102	119.5	146	159	182	255
L,	95	111.5	138	150	171	240
l,	30	35	45	50	56	75
t	10	15	15	20	25	20
t,	12	13.5	20	20	21	27.5

Dave	o Imam	.1			SI	ze		
Dore	es [mm	'1	01	0	1	2	3	4
	d 4151 -	d _{min}	10	15	22	32	35	40
Side	u ···	d _{max}	20	25	35	45	55	65
EAS*-	at 60.70	d _{P min}	12	15	22	28	32	40
	d _p (0,7) -	d _{P max}	20	25	30	40	50	65
side	al 3)	d _{3 min}	15	19	20	28	35	45
S	d ₃ 3) -	d _{3 max}	28	35	45	50	55	80
S	A 3)	d _{4 min}	15	19	20	28	35 ⁶⁾	45
6	d ₄ 3)	d _{4 max}	28	38	45	50	60 ⁸⁾	75
ROBA®-ES	al 30	d _{s min}	8	10	12	14	20	38
R	d ₅ ³⁾ -	d _{5 max}	28	38	45	55	60	80

We reserve the right to make dimensional and constructional alterations.





20

1) See Technical Data, limit torque for overload M_a.



Technical data				Size 1)				
ecrimical data				03	02			
	Type 450.5	M _G	[Nm]	0.65 - 1.30	2 - 5			
Limit torques for overload ¹⁾	Type 450.6	Ma	[Nm]	1.30 - 2.60	5 - 10			
Overload	Type 450.7	Mg	[Nm]	2.00 - 3.80	6 - 15			
Max. speed		n _{max}	[rpm]	4000	4000			
Thrust washer strok	e on overload		[mm]	0.8	1.0			

Mana mamanta a	finantia and u		ibto	Si	ze
Mass moments o	r inertia and v	veig	ints	03	02
	Type 45010	1	[10 ⁻³ kgm ²]	0.027	0.054
the state	Type 45020	1	[10 ⁻³ kgm ²]	0.025	0.051
łub-side	Type 45011	1	[10 ⁻³ kgm ²]	0.028	0.058
	Type 45021	1	[10 ⁻³ kgm ²]	0.026	0.055
Pressure flange-side	Type 450	1	[10 ⁻³ kgm ²]	0.008	0.018
	Type 45010	m	[kg]	0.18	0.28
Majahta	Type 45020	m	[kg]	0.17	0.26
Veights	Type 45011	m	[kg]	0.20	0.32
	Type 45021	m	[kg]	0.19	0.30

Tensioning screws and screw-on bores			Size		
rensioning screv	vs and screw-on t	ore	S	03	02
	Number, dimensions	M	[mm]	4 x M3	4 x M3
Tensioning screws in cone bushing	Wrench opening	SW	[mm]	5.5	5.5
in cone busining	Tightening torque	TA	[Nm]	1	1
Screw-on bores in pressure flange	Number, dimensions	s	[mm]	6 x M3	6 x M3

Dimensions [mm]		Si	ze
Dimensions	mmj	03	02
А		7.2	9.5
a 2)		2	2
a _o		4.5	5.0
a,		3.0	3.2
b		5	5
C,		20.5	25
E		40	47
e _{h5} 4)		30	37
F		37	42
F,		45	50
f		26	30
f _{1 h8}		17	25
f ₂		=	3
f ₄		-	37
* # for the control	9,	11.5	15.5
Minimum shaft length	9,	25.5	30.5
	98	41.5	50.5
h		24	29
h,		40	49
k,		2	2
L 6)		28.5	34.5
L, ⁰⁾		44.5	54.5
m		35	42

		Size		
Bores [mm]		03	02	
-	d _{min}	6	8	
d d _{max}	d _{max}	12	15	
- A	d _{p min}	6	8	
d _p 3)	d _{p max}	11	16 5)	

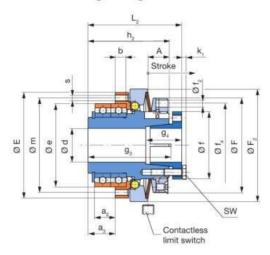
We reserve the right to make dimensional and constructional alterations.

- Further sizes for smaller and larger torques available on request
 Mounting tolerance + 0.1
 The position of the keyway to the mounting bore "s" in the pressure flange is not defined. Defined position available on request
 Tolerance user-side H7
- 5) Up to Ø 14 keyway acc. DIN 6885/1, over Ø 14 keyway acc. DIN 6885/3
 6) Dimensions in untensioned condition (shorter in tensioned condition)



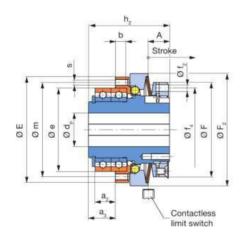
EAS®-NC double bearing design with cone bushing

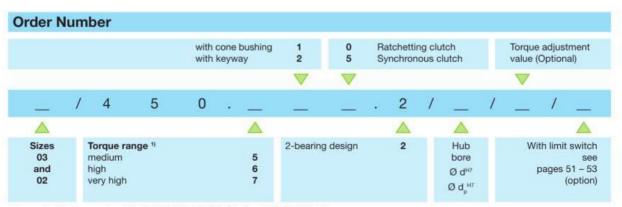
Type 450._1_.2 Sizes 03 and 02



EAS®-NC double bearing design with keyway

Type 450._2_.2 Sizes 03 and 02





Example: Order number 02 / 450.610.2 / 15 / 8 / limit switch 055.002.5

1) See Technical Data, limit torque for overload M_a



To aliminal plata				Size 1)		
Technical data		03	02			
	Type 450.52	M _g	[Nm]	0.65 - 1.30	2 - 5	
Limit torques for overload ¹⁾	Type 450.62	M _g	[Nm]	1.30 - 2.60	5 - 10	
	Type 450.72	M _G	[Nm]	2.00 - 3.80	6 - 15	
Max. speed		n _{max}	[rpm]	4000	4000	
Thrust washer strol	e on overload		[mm]	0.8	1.0	

	finantia and u		ala de la	Size	1
Mass moments o	r inertia and v	veiç	ints	03	02
this state	Type 45012	1	[10 ⁻³ kgm ²]	0.028	0.058
Hub-side	Type 45022	1	[10 ⁻³ kgm ²]	0.026	0.055
Pressure flange-side	Type 4502	1	[10 ⁻³ kgm ²]	0.008	0.018
\a/_!_L	Type 45012	m	[kg]	0.13	0.31
Weights	Type 45022	m	[kg]	0.18	0.29

Tensioning screws and screw-on bores			Size		
rensioning screv	vs and screw-on i	ore	S	03	02
	Number, dimensions	M	[mm]	4 x M3	4 x M3
Tensioning screws in cone bushing	Wrench opening	sw	[mm]	5.5	5.5
in concluding	Tightening torque	T	[Nm]	1	1
Screw-on bores in pressure flange	Number, dimensions	s	[mm]	6 x M3	6 x M3

		Si	ze
Dimensions	(mm)	03	02
Α		7.2	9.5
a ₂ 2)		9	9
a ₃		11.5	12
b		5	5
E		40	47
e _{hs} 4)		30	37
F		37	42
F ₂		45	50
f		26	30
f ₂		*	3
f ₄		-	37
Minimum	g ₃	32.5	37.5
shaft length	9,	11.5	15.5
h ₂		31	36
k,		2	2
L ₂ ⁶⁾		35.5	41.5
m		35	42

r		Si	ze
Bores [mm]		03	02
	d _{min}	6	8
d	d _{max}	12	15
el 31	d _{P min}	6	8
d _p ³⁾	d _{p max}	11	16 59

We reserve the right to make dimensional and constructional alterations.

- Further sizes for smaller and larger torques available on request
 Mounting tolerance + 0.1
 The position of the keyway to the mounting bore "s" in the pressure flange is not defined. Defined position available on request
 Tolerance user-side H7
 Up to Ø 14 keyway acc. DIN 6885/1, over Ø 14 keyway acc. DIN 6885/3
 Dimensions in untensioned condition (shorter in tensioned condition)



EAS®-NC with steel bellows coupling

Type 453.___.0 Sizes 03 and 02

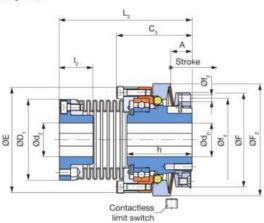
EAS®-side cone bushing, Steel bellows-side cone bushing Type 453._1_.0

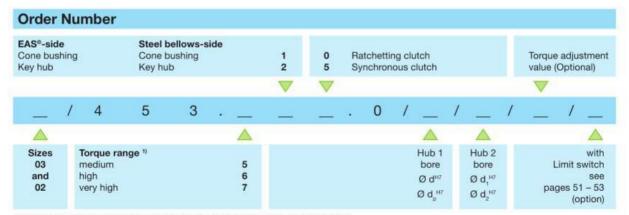
SW, k, Contactless k, SW

EAS®-side key hub,

Steel bellows-side key hub

Type 453. 2 .0





Example: Order number 02 / 453.615.0 / 15 / 15 / 8 / limit switch 055.002.5

1) See Technical Data, limit torque for overload Ma



Tooksiaal data				Size 1)	
Technical data				03	02
	Type 453.50	M _G	[Nm]	0.65 - 1.30	2 - 5
Limit torques for overload 1)	Type 453.60	M _g	[Nm]	1.30 - 2.60	5 - 10
OTOTION	Type 453.70	M _G	[Nm]	2.00 - 3.80	6 - 15
Max. speed		n _{max}	[rpm]	4000	4000
Thrust washer stro	ke on overload		[mm]	0.8	1.0
Nominal torques, st	eel bellows coupling	T _{KN}	[Nm]	12	25
	axial	ΔK _a	[mm]	0.2	0.3
Permitted misalignments	radial	ΔK,	[mm]	0.1	0.1
insungiments	angular	ΔK _w	[°]	2	2

			to to a	Siz	ze
Mass moments	or inertia and v	veig	ints	03	02
Unit state	Type 45310	1	[10 ⁻³ kgm ²]	0.027	0.054
Hub-side	Type 45320	1	[10 ⁻³ kgm ²]	0.025	0.051
	Type 45310		[10 ⁻³ kgm ²]	0.027	0.063
Steel bellows-side	Type 45320	1	[10 ⁻³ kgm ²]	0.025	0.057
Malaba.	Type 45310	m	[kg]	0.27	0.45
Weights	Type 45320	m	[kg]	0.24	0.39

Tourisation comme			Size		
Tensioning screv	NS			03	02
	Number, dimensions	M	[mm]	4 x M3	4 x M3
In cone bushing EAS®-side	Wrench opening	sw	[mm]	5.5	5.5
and dide	Tightening torque	T	[Nm]	1.3	1.3
	Number, dimensions	M,	[mm]	4 x M3	4 x M3
In cone bushing steel bellows-side	Wrench opening	SW,	[mm]	5.5	5.5
oteor believite dide	Tightening torque	TA	[Nm]	1.3	1.3

moncione	mm1	Si	ze
imensions	(11111)	03	02
A		7.2	9.5
C ₃		28	33.5
D,		30	36
E		40	47
F		37	42 50 30
F ₂		45	
f		26	
f ₂		-	3
f ₄		н	37
Minimum	9,	11.5	15.5
shaft length	g _s	12.5	16
h		24	29
k,		2	2
L ³⁾		28.5	34.5 70.5
L, 3)		58.5	
L ₂		49.3	59
I, 3)		14	21
l ₂		9.5	15

Baras	ores [mm]		Size				
bores			03	02			
	4	d _{min}	6	8			
d d _{P min}	d _{max}	12	15				
		6	8				
	d _{p max}	11	16 ²⁾				
	d _{1 min}	6	8				
-sid	d,	d _{1 max}	12	15			
Steel bel- lows-side	d ₂	d _{2 min}	6	8			
		d _{2 max}	11	16 2)			

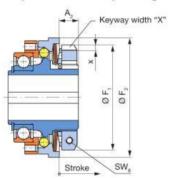
We reserve the right to make dimensional and constructional alterations.

- Further sizes for smaller and larger torques available on request
 Up to Ø 14 keyway acc. DIN 6885/1, over Ø 14 keyway acc. DIN 6885/3
 Dimensions in untensioned condition (shorter in tensioned condition)



EAS®-compact® Options

EAS®-compact® with adjusting nut for radial torque adjustment



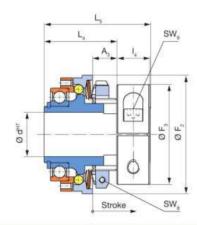
The EAS®-compact® can be equipped with an adjusting nut for radial torque adjustment if the clutch cannot be accessed axially due to narrow installation conditions.

On this variant, the graduation for reading and adjusting the torque is mounted radially visible on the outer diameter.

Dimensions [mm]	Size						
Dimensions [mm]	01	0	1	2	3		
A ₂	12	13.5	16	17	20.5		
F,	61	73	88	104	125		
F ₂	70	85	100	115	135		
X	8	8	10	10	10		
X	3.5	3.5	4	4	4		

EAS®-compact® with clamping ring

EAS®-compact® clutches with clamping ring hub can be mounted extremely quickly and easily onto the shaft. The slotted clamping ring is tensioned using one single screw. Due to the equipment with an adjusting nut for radial torque adjustment, the limit torque for overload can be altered even in installed condition.



Dimensions formal					
Dimensions [mm]	01	0	1	2	3
A ₃	15.5	19	20.5	23.5	26
F ₂	70	85	100	115	135
F ₃	60	72	84	97	115
L ₄	43.5	53.5	63.5	70.5	80.5
L,	65	77	90	103	117
l,	18	22	26	32	36

Davis [mm]				Size		
Bores [mi	Bores [mm]	01	0	1	2	3
d H7 1)	d _{min}	10	15	22	32	35
	d	25	32	40	45	55

1) For transmittable torques dependent on bore, see Table 1.

			Size		
Bore	01	0	1	2	3
Ø 10	44	(4)	197	12	¥
Ø 12	52	1.00		- 1	5
Ø 14	61	-	-	34	4:
Ø 16	69	101		7	7
Ø 18	78	113	141	/4	ė.
Ø 20	87	126	170	-	Ť.
Ø 22	96	138	199	12	Ţ.
Ø 25	109	168	226	327	*
Ø 28	-	201	253	366	523
Ø 30	-	216	290	420	561
Ø 32	9	230	325	470	598
Ø 35	-		355	515	700
Ø 38	- 8		386	559	798
Ø 40	-	3 4 .1	406	588	840
Ø 45	п	955	570.	661	945
Ø 50	-		(#)	#	1050
Ø 55	50	U.S.	(=)	17.	1155

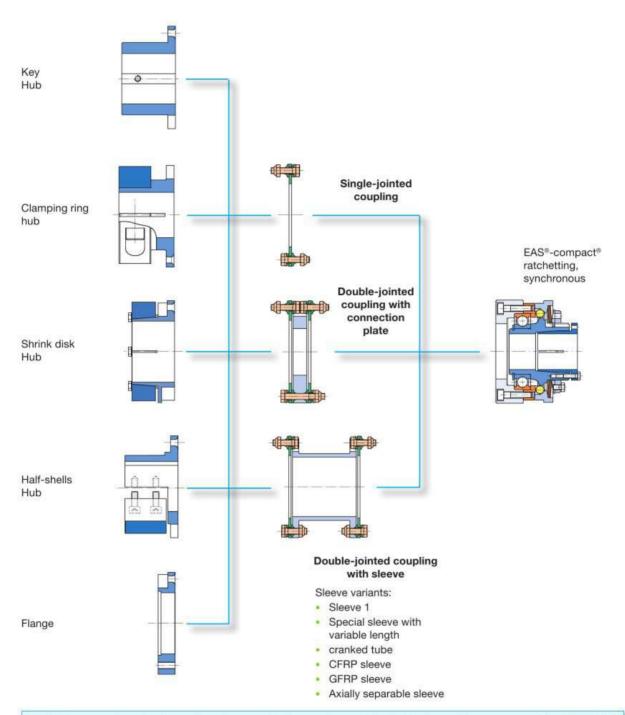
Table 1

C				Size					
Screws			01	0	1	2	3		
Locking screw in adjusting nut	Number, dimensions	M _s	[mm]	1 x M4	1 x M5	1 x M6	1 x M6	1 x M8	
	Wrench opening	SW _a	[mm]	3	4	5	5	6	
in adjusting nut	Tightening torque	TA	[Nm]	3	5.5	9.5	9.5	23	
	Number, dimensions	M _o	[mm]	1 x M6	1 x M8	1 x M10	1 x M12	1 x M14	
In the clamping ring	Wrench opening	SW.	[mm]	5	6	8	10	12	
	Tightening torque	T,	[Nm]	16	40	79	135	220	



EAS®-compact® Options

EAS®-Compact® torsionally rigid Modular Structure



All EAS®-compact® ratchetting and synchronous clutches can be combined with almost all components of the ROBA®-DS backlash-free shaft coupling. For a current selection of different Types, please see pages 16 and 17.

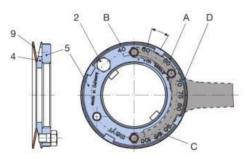
We are happy to advise you on the dimensioning and configuration of your optimum design.



Readable Torque Adjustment

The EAS®-compact®overload clutch offers easily readable torque adjustment on the adjusting nut (for Sizes 01 to 3). This readability makes adjusting the torque far more simple, and also allows easy checks on the set release value on the installed clutch.

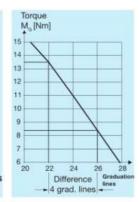
- The limit torque can be finely adjusted and accurately read due to the adjusting nut with the fine thread and the easily-readable graduation scale.
- The positive-locking (or frictionally-locking) safeguard on the adjusting nut protects against self-turning, inadvertent adjustment of the set limit torque. The integral blocking protection prevents the cup springs from becoming spring-bound.



Illustrations 1: EAS®-compact® ratchetting and synchronous clutch

Move to operating range Graph of spring characteristic curve Operating Spring path S

Fig. 3 (The diagram only serves as an example)



(The diagram only serves as an example)



Depending on the drive and the drive constellation, torque peaks (e.g. via start-up torque impacts on asynchronous motors) can occur which lie substantially above the system (motor) operating torque. This behaviour is to be taken into account customer-side when dimensioning or adjusting the clutch.

Torque Adjustment

Adjustment takes place by turning the adjusting nut (5) (Sizes 03 to 3) or the set screws (6) (Sizes 4 and 5).

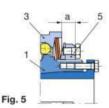
The installed cup springs (9) are operated in the negative range of the characteristic curve (Fig. 3). A stronger pre-tension produces a dropping in spring force. Turning the adjusting nut (5) (Sizes 03 to 3) or the set screws (6) (Sizes 4 and 5) clockwise therefore produces a decrease in spring force. Turning it anti-clockwise produces an increase in torque (facing direction towards the adjusting nut (5) – Figs. 1 and 2).

If no other torque adjustment is requested customer-side, the EAS®-compact® ratchetting and synchronous clutches are generally set and marked (calibrated) manufacturer-side to approx. 70 % of the respective maximum torque. The respective torque adjustment or the adjustable torque range are visible on the type tag.

A control "spring operation in the operating range" can be carried out via the dimension "a".

EAS®-compact® ratchetting and synchronous clutch (Sizes 01 - 3): Dimension "a" is the distance between the adjusting nut facing-side (5) to the thrust washer facing-side (3) (Fig. 5).

For the corresponding data, please see the Installation and Operational Instructions.



EAS®-NC Sizes 03 and 02 must be adjusted according to the Adjustment Diagram (please order if necessary) if no adjustment or calibration was made manufacturer-side.

EAS®-NC Size 03 (Fig. 7):

- . Unscrew both set screws (8) from the adjusting nut (5).
- Grease the thread surfaces on the adjusting nut (5) and the hub (1).
- Set the adjusting nut (5) to the required dimension "a" (acc. Adjustment Diagram) using a hook wrench.
- Paint both set screws (8) with Loctite 243, screw them into the adjusting nut (5) and tighten them.

EAS®-NC Size 02 (Fig. 8 and Fig. 4):

- · Loosen the locking screw (2).
- Grease the thread and contact surfaces on the adjusting nut (5), the locking ring (4) and the hub (1).
- The adjusting nut (5) is adjusted by hand up to contact on the cup springs (9).
- Continue to turn until the four notches on the circumference of the adjusting nut (5) and the notches in the locking ring (4) align.
- Turn the adjusting nut (5) further using a face wrench to the number of graduation lines which equal the required torque (Fig. 4, number of graduation lines in the Adjustment Diagram). The 4 notches on the circumference of the adjusting nut (5) and on the locking ring (4) must be in the same position.
- Paint the locking screw (2) with Loctite 243 and screw it into the adjusting nut (5).

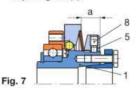


Fig. 8





Adjusting the Torque

Sizes 01 to 3 (Figs. 1, 2 and 6):

 Convert the required torque (acc. formula below) in percent of the maximum adjustment value.

Required torque adjustment	- x 100 = Adjustment in %
Max. torque adjustment	- x 100 = Adjustment in %
(see Table Technical Data)	

- . Loosen the locking screw (2) in the adjusting nut (5).
- Turn the adjusting nut (5) clockwise or anti-clockwise according to the engraved adjustment scale (Figs. 1 and 2) using a hook wrench or a face wrench, until the required torque is set.
- The required torque results from the marking overlap (D) on the locking ring (4) and the percent value (C) on the adjusting nut (5), see Fig. 1.
- Paint the locking screw (2) with Loctite 243 and screw it into the adjusting nut (5); the 4 notches (A) in the adjusting nut (5) and the notches (B) in the locking ring (4) must be in the same position (Fig. 1). Correct slightly if necessary.

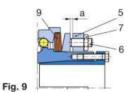
Example:

EAS®-compact® Size 3, Type 490.610.0 (M_a max. = 350 Nm): Torque pre-adjustment = 70 % of M_a max. = 245 Nm. The adjustment should be increased from 245 Nm to 280 Nm.

 Define the torque adjustment in percent of M_g max, using the formula below:

280	v 100 - 80 0/
350	x 100 = 80 %

Turn the adjusting nut (5) according to the facing-side graduation scale
 Fig. 1) anti-clockwise from 70 % to 80 % on the adjustment scale using a face wrench.



Size 4 (Figure 9):

The torque is changed exclusively via the set screws (6) and not via the adjusting nut (5).

- . Loosen all hexagon nuts (7).
- Adjust all set screws (6) evenly to the required dimension "a" using a hexagon socket wrench (dimension "a" see adjustment table glued onto the clutch).
- Counter the set screws (6) again using hexagon nuts (7).



After de-installing the clutch (e.g. due to cup spring replacement or changes to the cup spring layering), the clutch must be re-adjusted.

Permitted Bearing Load

The output element is centred on the deep groove ball bearing (tolerance H7/h5) and bolted together with the pressure flange (3).

If the resulting radial force from the output element is anywhere near the centre of the ball bearing and under the maximum permitted radial load according to Table 1, an additional bearing for the output element is unnecessary.

No appreciable axial forces (see Table 1) should be transferred from the output element onto the clutch pressure flange (3).

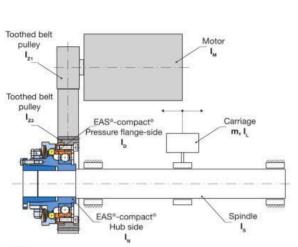
Permitted		Size									
bearing load			03	02	01	0	1	2	3	4	5
Axial forces	FA	[kN]	0.12	0.28	0.65	1	1.5	2.4	4.2	5	7.7
Radial forces	FR	[kN]									
1-bearing desig	n		0.1	0.25	0.65	1	1.5	2.4	4.2	5	17
2-bearing desig	n		0.15	0.375	1	1.5	2.25	3.6	6.3	7.5	11.5
Transverse force torques*	Mo	[Nm]	0.5	1.5	5	10	20	30	40	50	70

Table 1

 Torques, which put strain on the deep groove ball bearing due to the non-centric axial forces having an effect on the pressure flange.



Size Selection, Energy Calculation, Torque Adjustment for Horizontal Servo Axes



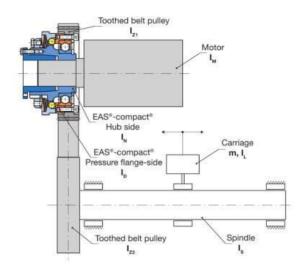


Fig. 1 Fig. 2

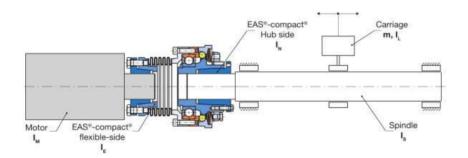


Fig. 3

Configuration Fig. 1	Configuration Fig. 2	Configuration Fig. 3	
Total mass moment of inertia withou	rt EAS®-compact® clutch		
$I_g = I_M + I_{Z1} + (I_{Z2} + I_S + I_L) \cdot (\frac{n_2}{n_L})^2$	$I_0 = I_M + I_{21} + (I_{22} + I_S + I_L) \cdot (\frac{n_2}{n_L})^2$	$I_g = I_M + I_{Ku} + I_S + I_L$	[kgm²] (1
I _L from equation (7)	I _L from equation (7)	I _L from equation (7)	
Mass moment of inertia drive-side re	eferring to the shaft with the EAS®-compact® of	clutch	
$I_1 = I_D + I_{22} + (I_{21} + I_{M}) \cdot (\frac{n_1}{n_2})^2$	$I_{\tau} = I_M + I_N$	$I_{_{\parallel}} = I_{_{M}} + I_{_{E}}$	[kgm²] (2
Mass moment of inertia output-side	(spindle-side) referring to the shaft with the E	AS®-compact® clutch	
$I_2 = I_N + I_S + I_L$	$I_2 = I_0 + I_{z_1} + (I_{z_2} + I_s + I_L) \cdot (\frac{n_2}{n_1})^2$	$I_2 = I_N + I_S + I_L$	[kgm²] (3
I, from equation (7)	I _L from equation (7)	I _L from equation (7)	
Clutch pre-selection			
$M_{ert} = 1.5 \cdot M_2$ M_3 from equation (4)	$M_{ert.} = 1.5 \cdot M_1$	$M_{ert} = 1.5 \cdot M_{_1}$	[Nm]



your reliable partner

Torque on the spindle $M_2 = M_1 \cdot \frac{n_1}{n_2}$ Carriage feed rate $v = \frac{p \cdot n_2}{6 \cdot 10^4}$ Angular speed of the motor shaft ω_1 and the $\omega_1 = \frac{n_1 \cdot \pi}{30} \qquad \omega_2 = \frac{n_2 \cdot \pi}{30}$ Mass of the carriage reduced on the spinor $I_L = m \cdot \frac{v^2}{\omega_2^2}$	As configuration Fig. 1	As configuration Fig. 1 As configuration Fig. 1	[Nm]	(4)
Carriage feed rate $v = \frac{\rho \cdot n_2}{6 \cdot 10^4}$ Angular speed of the motor shaft ω_1 and the $\omega_1 = \frac{n_1 \cdot \pi}{30}$ $\omega_2 = \frac{n_2 \cdot \pi}{30}$ Mass of the carriage reduced on the spinor	As configuration Fig. 1 he spindle ω_2 As configuration Fig. 1		N Marie	(4
$v = \frac{p \cdot n_2}{6 \cdot 10^4}$ Angular speed of the motor shaft ω_1 and the $\omega_1 = \frac{n_1 \cdot \pi}{30}$ $\omega_2 = \frac{n_2 \cdot \pi}{30}$ Mass of the carriage reduced on the spinor	he spindle ω_2	As configuration Fig. 1	[<u>m</u>]	
Angular speed of the motor shaft ω_1 and the $\omega_1 = \frac{n_1 \cdot \pi}{30}$ $\omega_2 = \frac{n_2 \cdot \pi}{30}$ Mass of the carriage reduced on the spinor	he spindle ω_2	As configuration Fig. 1	[m]	
$\omega_1 = \frac{n_1 \cdot \pi}{30}$ $\omega_2 = \frac{n_2 \cdot \pi}{30}$ Mass of the carriage reduced on the spinor	As configuration Fig. 1			(5
Mass of the carriage reduced on the spino				
200	dle	As configuration Fig. 1	[s ⁻¹]	(6
$I_{L} = m \cdot \frac{V^{2}}{\omega_{2}^{2}}$				
v from equation (5), ω ₂ from equation (6)	As configuration Fig. 1	As configuration Fig. 1	[kgm²]	(7
Energy on collision without EAS®-compa	ct® clutch			
	or older			
$W_{g} = \frac{1}{2} \cdot I_{g} \cdot \omega_{1}^{2}$ $I_{g} \text{ from equation (1), } \omega_{1} \text{ from equation (6)}$	As configuration Fig. 1	As configuration Fig. 1	[J]	(8
Energy on collision with EAS®-compact®	clutch			
	$W_2 = \frac{1}{2} \cdot I_2 \cdot \omega_1^2$	$W_2 = \frac{1}{2} \cdot I_2 \cdot \omega_1^2$	[J]	(9
I_s from equation (3), ω_s from equation (6)	I₂ from equation (3), ω₁ from equation (6)	I, from equation (3), ω , from eq.(6)		
Remaining residual energy	** 18 344 1 35 23			
$W_{R} = \frac{W_{2}}{W_{0}} \cdot 100$ $W_{0} = \frac{W_{2}}{W_{0}} \cdot 100$ $W_{0} = \frac{W_{2}}{W_{0}} \cdot 100$	As configuration Fig. 1	As configuration Fig. 1	[%]	(1
W _g from equation (8), W _g from equation (9) Uncoupled energy				
$\Delta W = W_g - W_z$ $\Delta W = 100 - W_R$	As configuration Fig. 1	As configuration Fig. 1	[J] [%]	(1:
W_g from equation (8), W_g from equation (9),	W _a from equation (10)		[vol	111
Required disengagement torque in the acc				
$M_{A} = M_{B} \cdot \frac{I_{2}}{I_{2} + I_{1}} \cdot \frac{n_{1}}{n_{2}}$	Speed ratio $\frac{n_1}{n_2}$ not applicable.	Speed ratio $\frac{n_1}{n_2}$	[Nm]	(1
$\frac{1}{1}$ from equation (2), $\frac{1}{1}$ from equation (3)	- 1.15	not applicable		
Required disengagement torque in the acc	celeration phase (axis in any direction)			
$M_A = [(M_B \cdot \frac{n_1}{n_2} - M_I) \cdot \frac{I_2}{I_2 + I_1} + M_L] \times 1.2$	$M_A = [(M_B - M_L \cdot \frac{n_2}{n_1}) \cdot \frac{l_2}{l_2 + l_1} + M_L \cdot \frac{n_2}{n_1}] \times 1.2$	$M_A = [(M_B - M_L) \cdot \frac{I_2}{I_2 + I_1} + M_L] \times 1.2$	[Nm]	(1
M _L from equation (15)	M _L from equation (15)	M _L from equation (15)		
Load torque from carriage mass in any dir	rection			
$M_{\scriptscriptstyle L} = \frac{m \cdot g \cdot sin\alpha \cdot p}{2 \cdot \pi \cdot 1000}$	As configuration Fig. 1	As configuration Fig. 1	[Nm]	(1
α Spindle				
111111111111111111111111111111111111111				
Limit torque adjustment				
The state of the s	$M_G = 1.5 \cdot M_1$	$M_g = 1.5 \cdot M_g$ M_g from equation (4)	[Nm]	(1



Toothed belt

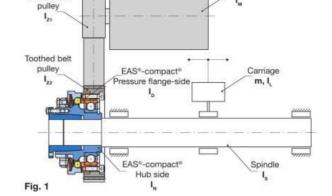
Technical explanations

Calculation Example

Configuration as shown in Fig. 1

Data:

Mass of the carriage	m	= 560 kg
Mass moment of inertia of the motor	I _M	$= 0.0037 \text{ kgm}^2$
Mass moments of inertia of the	I _{z1}	$= 0.0006 \text{ kgm}^2$
Toothed belt pulleys	1,22	= 0.01132 kgm ²
Mass moment of inertia of the spindle	I _s	= 0.00067 kgm ²
Drive speed of the motor	n,	= 2000 rpm
Speed of the spindle	n ₂	= 1000 rpm
Pitch of the spindle	p	= 10 mm
Nominal torque of the motor	M,	= 14 Nm
Max. torque of the motor	Ma	= 40 Nm



Clutch pre-selection

$$M_{ert} = 1.5 \cdot M_2$$
 M_a from equation (4)

$$M_{ext} = 1.5 \cdot 28 = 42$$

Selected:

EAS®-compact® Size 0, Type 490.610.0 Torque range M_G = 20 ÷ 50 Nm

(see Technical Data, page 9)

Total mass moment of inertia of the EAS®-compact®

Hub side I, = 0.000531 kgm2 (see Techn. Data, page 9)

Pressure flange side $I_D = 0.000234 \text{ kgm}^2$ (see Techn. Data, page 9)

Total mass moment of inertia without EAS®-compact® clutch

$$I_g = I_M + I_{21} + (I_{22} + I_S + I_L) \cdot (\frac{n_2}{n_1})^2$$
 I_L from equation (7)

$$I_g = 0.0037 + 0.0006 + (0.01132 + 0.00067 + 0.00142) \cdot (\frac{1000}{2000})^2$$

 $l_g = 0.00765$

[kgm²] (1)

Mass moment of inertia drive-side referring to the shaft with the EAS®-compact® clutch

$$I_1 = I_D + I_{22} + (I_{21} + I_M) \cdot (\frac{n_1}{n_2})^2$$

$$I_1 = 0.000234 + 0.01132 + (0.0006 + 0.0037) \cdot (\frac{2000}{1000})^2$$

I, = 0.0287

[kgm²] (2)

Mass moment of inertia output-side (spindle-side) referring to the shaft with the EAS®-compact® clutch

Torque on the spindle

$$M_2 = M_1 \cdot \frac{n_1}{n_2} = 14 \cdot \frac{2000}{1000} = 28$$
 [Nm] (4)

Carriage feed rate

$$v = \frac{p \cdot n_2}{6 \cdot 10^4} = \frac{10 \cdot 1000}{6 \cdot 10^4} = 0.1667 \qquad \left[\frac{m}{s}\right] \quad (5)$$

Angular speed of the motor shaft ω , and the spindle ω ,

$$v_1 = \frac{\mathsf{n}_1 \cdot \mathsf{n}}{30} \qquad = \frac{2000 \cdot \mathsf{n}}{30} = 209$$

Motor

$$\omega_2 = \frac{n_2 \cdot \pi}{30} = \frac{1000 \cdot \pi}{30} = 104.7$$

[s-1] (6)

Mass of the carriage reduced on the spindle

$$I_L = m \cdot \frac{v^2}{\omega_2^2}$$
 = $560 \cdot \frac{0.1667^2}{104.7^2} = 0.00142$ [kgm²] (7)

v from equation (5), ω_{o} from equation (6)

Energy on collision without EAS®-compact® clutch

$$W_g = \frac{1}{2} \cdot I_g \cdot \omega_1^2 = \frac{1}{2} \cdot 0.00765 \cdot 209^2 = 167$$
 [J] (8)

I, from equation (1), ω, from equation (6)

Energy on collision with EAS®-compact® clutch

$$W_{2} = \frac{1}{2} \cdot I_{2} \cdot \omega_{2}^{2} = \frac{1}{2} \cdot 0.00262 \cdot 104.7^{2} = 14$$
 [J] (9)

 I_z from equation (3), ω_z from equation (6)

Remaining residual energy

$$W_{R} = \frac{W_{2}}{W_{g}} \cdot 100 = \frac{14}{167} \cdot 100 = 8.4$$
 [%] (10)

Uncoupled energy

$$\Delta W = W_0 - W_2$$
 = 167 - 14 = **153** [J] (11)
 $\Delta W = 100 - W_0$ = 100 - 8.4 = **91.6** [%] (12)

Required disengagement torque in the acceleration phase (horizontal axis)

$$M_A = M_B \cdot \frac{I_2}{I_2 + I_1} \cdot \frac{n_1}{n_2} \cdot \frac{I_1 \text{ from equation (2)}}{I_2 \text{ from equation (3)}}$$

$$M_A = 40 \cdot \frac{0.00262}{0.00262 + 0.0287} \cdot \frac{2000}{1000} = 6.7 \text{ [Nm] (13)}$$

Limit torque adjustment

$$M_g = 1.5 \cdot M_g = 1.5 \cdot 28 = 42$$
 [Nm] (16)

Condition: The disengagement torque 1.2 \cdot M_A = 1.2 \cdot 6.7 = 8.04 Nm is smaller than the torque M_G = 42 Nm set on the clutch.



Keys

-		
l _a	[kgm²]	Total mass moment of inertia without EAS®-compact® clutch
ĺ,	[kgm²]	Mass moment of inertia drive-side referring to the shaft with the EAS®-compact® clutch
1,	[kgm²]	Mass moment of inertia output-side (spindle-side) referring to the shaft with the EAS®-compact® clutch
I _M	[kgm²]	Mass moment of inertia of the motor
I _{z1}	[kgm ²]	Mass moment of inertia of the motor-side toothed belt pulley
122	[kgm ²]	Mass moment of inertia of the second toothed belt pulley
Is	[kgm²]	Mass moment of inertia of the spindle
I _L	[kgm ²]	Mass of the carriage reduced on the spindle
I,	[kgm²]	Mass moment of inertia of the EAS®-compact®, hub-side
I _D	[kgm²]	Mass moment of inertia of the EAS®-compact®, pressure flange-side
I _E	[kgm²]	Mass moment of inertia of the EAS®-compact®, flexible coupling
l _{Ku}	[kgm²]	Mass moment of inertia of the double shaft connection before installation of the EAS®-compact® clutch
M,	[Nm]	Motor nominal torque
M,	[Nm]	Torque on the spindle
MA	[Nm]	Required disengagement torque in the acceleration phase
M _B	[Nm]	Maximum motor torque
M _G	[Nm]	Limit torques for overload
M,	[Nm]	Load torque from the carriage mass in any direction
M _{ert.}	[Nm]	Required torque (pre-selection of the clutch)
g	[m·s-2]	Gravitational acceleration
m	[kg]	Carriage mass
n,	[rpm]	Drive speed on the motor (rapid movement)
n ₂	[rpm]	Spindle speed (rapid movement)
p	[mm]	Spindle pitch
V	[m·s-1]	Carriage feed rate
Wg	[J]	Total energy on collision without EAS®-compact® clutch
W ₂	[J]	Energy on collision with EAS®-compact® clutch
W _B	[%]	Remaining residual energy
ΔW	[J]	Uncoupled energy
ΔW	[%]	Uncoupled energy
ω_1	[S ⁻¹]	Angular speed of the motor shaft
ω_2	[S ⁻¹]	Angular speed of the spindle



Frictionally-locking Transmittable Torques

Table 1: Assignment of the bore diameters d₃/d₄ on the flexible coupling to the transmittable torque "T_R" EAS®-compact® synchronous and ratchetting clutches Types 494._0_._/494._1_._

		Boro				Si			
		Bore	- 4	01	0	1	2	3	4
		Ø 15	d ₃	34	-	-	-	-	-
			d ₄	56	10		- 5	-	-
		Ø 16	d ₃	36		-	-	-	*
		7 10	d ₄	62			-	-	-
		Ø 19	d ₃	43	79	•	-		*
		D 13	d ₄	81	141			-	
		Ø 20	d ₃	45	83	83	74	-	-
		D 20	d ₄	87	153	197			
		Ø 22	d ₃	50	91	91			51
		W 22	d ₄	100	177	228	-	-	-
		~ ~ ~	d ₃	54	100	100	2	2	27
		Ø 24	d ₄	120	203	261	15		-
		200	d _a	57	104	104	-	-	
		Ø 25	d ₄	125	216	279	-	-	-
		Nation of the last	d _a	63	116	116	208	2	2
		Ø 28	d,	135	256	332	300	. #	-
		-	d ₃	-	124	124	228	-	
		Ø 30	d ₄	E .	282	368	350	-	-
			d ₃	-	133	133	248		-
rictionally- ocking transmittable orques		Ø 32	d ₄		308	405	400		-
			d ₃		145	145	280	350	2
		Ø 35	d ₄		343	460		450	
				-	32/05/04/0		500		-
Clamping hub Ø d,		Ø 38	d ₃	T.	979	158	315	390	•
/alid for F7/k6			d ₄	*	373	513	600	500	*
ENWINE AND MAINTE		Ø 40	d ₃	2	-	166	340	420	2:
hrink disk hub Ø d		3000	d ₄	5.	10%	547	680	600	-
alid for H7/k6		Ø 42	d ₃	*	(*)	174	365	455	*
		~	d ₄	¥	*	577	730	720	-
	T _R [N	m] Ø 45	d ₃			187	404	505	545
	R	,	d ₄		*	617	790	850	1402
ho transmittable torsus		Ø 48	d ₃	¥	2.83	•	442	560	590
he transmittable torques of the clamping connection		W 40	d ₄	2	-		850	1000	1596
ake the max. tolerance		Ø 50	d ₃	=		a	470	600	630
packlash of the shaft tol-		Ø 50	d ₄	*	(*)		880	1180	1731
erance k6/ bores F7 or H7		0.50	d ₃	2	1848	7-7	-	640	662
nto account.		Ø 52	d ₄		-	- 3	-	1270	1873
f the tolerance backlash is		27.50	d ₃				-	705	710
arger, the torque decreas-		Ø 55	d ₄	+			-	1353	2095
S.			d ₃	2	12		-	-	764
107		Ø 58	d ₄	-			-	1428	2308
		151755	d ₃	# H	-	-	-	-	800
		Ø 60	d ₄	1	1.0	-		1471	2420
			d ₃			121		14/1	840
		Ø 62	d ₄		1974			- 127	2570
			d ₃		-				900
		Ø 65	d ₃	20	300	1 22	-	-	
							-		2750
		Ø 68	d ₃	5		33	5		954
		-	d ₄	*	*		-	-	2989
		Ø 70	d ₃	-		-	-	-	990
			d ₄	5	(5)	32	-	T.	3157
		Ø 72	d _a		(*)			- 8	1032
		012	d ₄	+	(34)			-	3306
		Ø 75	d ₃	25	522	1920	14	2	1095
		W 15	d ₄	7	1.00	(2)	:5	7	3550
		0.70	d ₃	*	*	(*)		-	1158
		Ø 78	d,	-		-	-	-	-
		20.22	d ₃	π-	-	-	-	-	1200
		Ø 80	d ₄	*			-	-	-



Limit Switch Type 055.00_.5 (Contactless)

Application

This device is used for measuring and monitoring axial and radial disengagement movements, e.g. on EAS®-clutches. It acts as a control sensor for electronic and mechanical sequences.

Function

When the sensor surface of the NAMUR sensor scans a metal control flag (damped), the signalling relay is triggered, is deenergised and drops. Contacts 1 - 2 are opened. Damping is possible from all sides.

Electrical Connection (Terminals)

1 - 2 - 3 Floating change-over contacts
 5 - 6 Connection input voltage

Design

The electronic amplifier is installed in a light metal housing. The limit switch is fixed using two screw-on mounting links attached diagonally with M4 cap screws.

Technical data

Input voltage 230 VAC, ±10 %, 50 - 60 Hz (dependent on design) 115 VAC, ±10 %, 50 - 60 Hz

24 VDC, PELV, ±5 %,

protected against reverse polarity, for overvoltage category II connection

Power consumption Max. 1.5 VA

Ambient temperature -10 °C up to +60 °C limit switch -25 °C up to +60 °C NAMUR sensor

Protection IP54

Conductor cross-section Max. 2.5 mm2 / AWG 14

Weight 400 g / 14 oz

Device fuses 0.1 A/fast acting at 24 VDC (in system)

Signalling relay Floating change-over contacts Contact load max. 250 VAC / 12 A

Contact load max. 250 VAC / 12 A Contact material AgNi 90/10 max. switching frequency 20 Hz at min. load, 0.1 Hz at max. load

ching distance S_n 2 mm, flush fitting, max. switching frequency 2 kHz, the zero point can be set per

1 mm by means of the lateral adjusting

screw SW 7

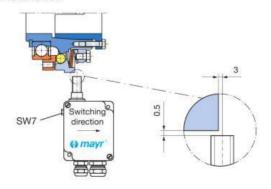
NAMUR sensor external Metal housing M12 x 1, switching

distance S_n 2 mm, flush fitting, max. switching frequency 2 kHz, stan-

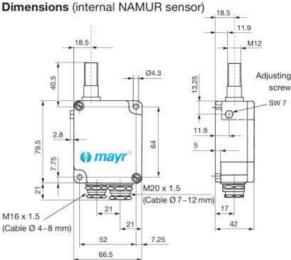
dard cable length 2 m, max. 100 m on special design, protec-

tion IP67

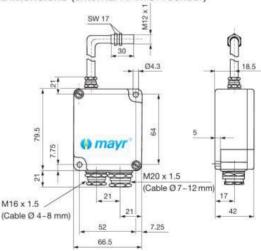
Installation







Dimensions (external NAMUR sensor)







Limit Switch Type 055.000.5 (Mechanical Operation)

Application

This device is used to monitor mechanical movements and end positions. It is a controlling sensor for electronic and mechanical sequences. It also detects axial disengagement movements, e.g. on EAS®-clutches.

Function

The pre-tensioned contact is discharged by actuating the switching lever:

Contacts 11 - 14 (21 - 24) open, contacts 11 - 12 (21 - 22) close.

Design

The microswitch is fitted into a light metal housing and is actuated by a switching lever. Operation is only possible in one direction. The limit switch is fixed using two screw-on mounting links attached diagonally with M4 cap screws.

Technical data

Contact 1 change-over contact

(special design: 2 change-over

contacts)

Switching power 250 VAC / 15 A (with 2 change-over

contacts: 10 A)

24 VDC / 6 A 60 VDC / 1.5 A 250 VDC / 0.2 A min. 12 VDC / 10 mA

Contact material AgSnO

Switching frequency

Max. 200 switching

operations/min
Ambient temperature:

-10 °C up to +85 °C

Protection IP54 Weight 275 g

the zero point can be moved right or

left by max. 5 mm

Switching travel Pretravel: min. 0.15 to 0.5 mm

Overtravel: max. 10 mm,

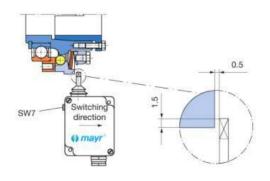
depending on the zero point setting

Different switching lever lengths as well as a design with 2 change-over

contacts are possible on request

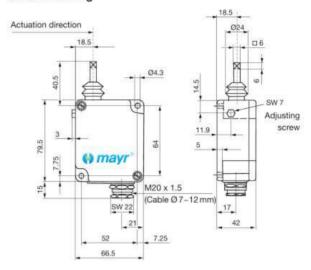
Installation

Special types

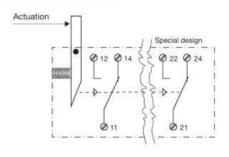




Detail drawing



Electrical connection



Order Number

0 5 5 . 0 0 0 . 5



Limit Switch Type 055.010.6 (Mechanical Operation, Multi-directional)

Application

The limit switch is used to monitor and measure axial or radial mechanical movements and adjustments e.g. on EAS®-clutches. The device is suitable for clutches with a minimum stroke of 1.1 mm with radial actuation and 0.9 mm with axial actuation.

Function

By actuating the metal tappet, contacts 11 - 12 are opened.

Electrical Connection (Terminals)

11 - 12NC contact

Technical data

Contact 1 x NC contact,

positive opening contacts

Contact (Special Design) additional 1 x NO contact, terminals

23 - 24, galvanically separated (Zb)

Contact-opening see Switching Travel Diagram Contact-closing see Switching Travel Diagram Contact-load

NC contact 250 VAC / 2.5 A 24 VDC / 1 A

min. 12 VDC / 10 mA Contact distance 250 VAC >1,25 mm axial, forced opening

Contact distance 24 VDC <1.25 mm, min. 0.5 mm

Ag90Ni10 Contact material

acc. DIN EN 60947-5-1 Max. input current

AC15 / DC13

Metal tappet travel max. 4 mm axial or radial

Switching frequency max. 100/min.

Mechanical lifetime 1 x 106 switching cycles, unloaded

1.5 mm² / AWG 16 Conductor cross-section -30 °C up to +80 °C Ambient temperature:

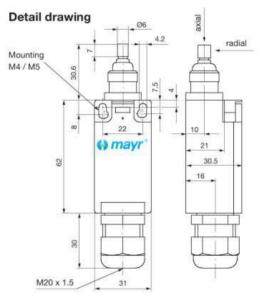
Protection

Protection insulation acc. Protection Class II

Housing thermoplastic, self extinguishing acc. UL94-V0

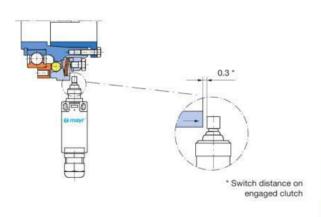
Weight 120 g / 4.2 oz



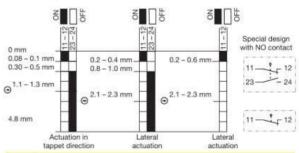


Fixed positioning for safety application with fixing screws 2 x M5

Installation



Switching travel diagram





Do not install switch so that it drags and observe max. actuation travel (travel of metal tappet).

Order Number

0 5.0 0.6



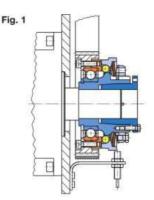
Installation Examples

EAS®-compact® short hub

The drive elements of the EAS®-compact® short hub are centred on the deep groove ball bearing and are screwed together with the pressure flange. If the resulting radial force from the drive element is anywhere near the centre of the ball bearing, an additional bearing for the drive element is unnecessary.

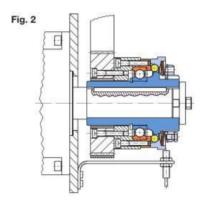


The screw quality and the tightening torque for the fixing screws of the drive element are to be selected so that the set limit torque can be safely transmitted using frictional locking.



EAS®-compact® long protruding hub

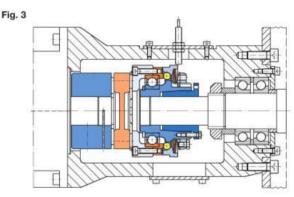
The EAS®-compact® long protruding hub is recommended for very wide drive elements or for elements with very small diameters. On a small diameter, the drive element is screwed together via a customer-side intermediate flange with the clutch pressure flange. Ball bearings, needle bearings or plain bearings are suitable as bearings for the drive element, depending on the installation situation and the installation space.



EAS®-compact® with flexible shaft coupling

The EAS®-compact® with a backlash-free, torsionally flexible and vibration-damping shaft coupling for the connection of two shafts. The couplingcompensates for axial, radial and angular shaft misalignments. In comparison to the EAS®-compact® with steel bellows coupling, this product is torsionally flexible to a small extent in the circumferential direction.

In the installation example on the right, the EAS®-compact® lastic is mounted backlash-free between the rotor and a ball screw spindle. The torque is transmitted backlash-free up to the point of disengagement and drops immediately on overload. The contactless limit switch (sensor) emits a signal to switch off the drive.

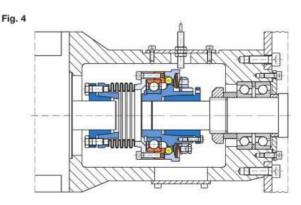


EAS®-compact® with steel bellows coupling

The EAS®-compact® with a torsionally rigid flexible steel bellows coupling for the connection of two shafts. The coupling compensates for axial, radial and angular shaft misalignments. It is torsionally rigid in the circumferential direction.

In comparison with the EAS®-compact® with ROBA®-D coupling, the EAS®-compact® with steel bellows coupling has a lower mass moment of inertia.

In the installation example on the right, the EAS®-compact® with steel bellows coupling is mounted between the rotor and a ball screw spindle. The torque is transmitted backlash-free up to the point of disengagement and drops immediately on overload. The contact-less limit switch (sensor) emits a signal to switch off the drive.





Product Summary

Torque Limiters/Overload Clutches

■ EAS®-compact®/EAS®-NC/EAS®-smartic®

Positive locking and completely backlash-free torque limiting clutches

■ EAS®-reverse

Reversing re-engaging torque limiting clutch

EAS®-element clutch/EAS®-elements

Load-disconnecting protection against high torques

■ EAS®-axial

Exact limitation of tensile and compressive forces

EAS®-Sp/EAS®-Sm/EAS®-Zr

Load-disconnecting torque limiting clutches with switching function

■ ROBA®-slip hubs

Load-holding, frictionally locked torque limiting clutches

■ ROBA®-contitorque

Magnetic continuous slip clutches

■ EAS®-HSC/EAS®-HSE

High-speed torque limiters for high-speed applications

shaft couplings

smartflex®/primeflex®

Perfect precision couplings for servo and stepping motors

■ ROBA®-ES

Backlash-free and damping for vibration-sensitive drives

ROBA®-DS/ROBA®-D

Backlash-free, torsionally rigid all-steel couplings

■ ROBA®-DSM

Cost-effective torque-measuring couplings



Electromagnetic Brakes/Clutches

ROBA-stop® standard

Multifunctional all-round safety brakes

ROBA-stop®-M motor brakes

Robust, cost-effective motor brakes

■ ROBA-stop®-S

Water-proof, robust monoblock brakes

ROBA®-duplostop®/ROBA®-twinstop®/ROBA-stop®-silenzio®

Doubly safe elevator brakes

■ ROBA®-diskstop®

Compact, very quiet disk brakes

■ ROBA®-topstop®

Brake systems for gravity loaded axes

ROBA®-linearstop

Backlash-free brake systems for linear motor axes

ROBA®-guidestop

Backlash-free holding brake for profiled rail guides

■ ROBATIC®/ROBA®-quick/ROBA®-takt

Electromagnetic clutches and brakes, clutch brake units

DC Drives

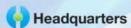
tendo®-PM

Permanent magnet-excited DC motors









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You can find the complete address for the representative responsible for your area under www.mayr.com in the internet.

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